

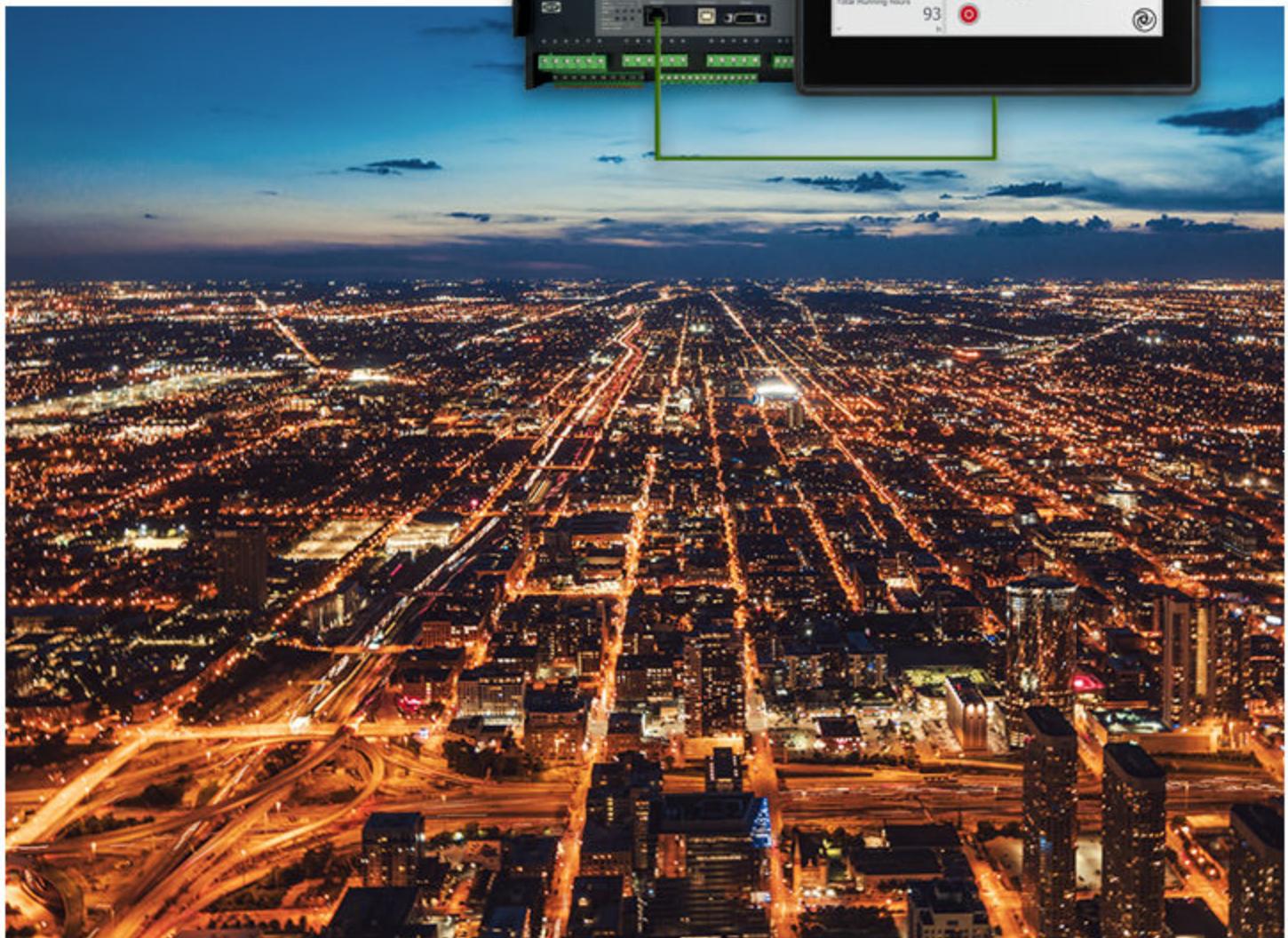
# AGC-4 Mk II

Genset, Mains, BTB, Group, and Plant controller

## Installation instructions



Improve  
Tomorrow



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# 1. General information

## 1.1 Warnings, legal information and safety

### 1.1.1 Symbols for hazard statements

#### DANGER!



**This shows dangerous situations.**

If the guidelines are not followed, these situations will result in death, serious personal injury, and equipment damage or destruction.

#### WARNING



**This shows potentially dangerous situations.**

If the guidelines are not followed, these situations could result in death, serious personal injury, and equipment damage or destruction.

#### CAUTION



**This shows low level risk situation.**

If the guidelines are not followed, these situations could result in minor or moderate injury.

#### NOTICE



**This shows an important notice**

Make sure to read this information.

### 1.1.2 Symbols for general notes

**NOTE** This shows general information.



**More information**

This shows where you can find more information.



**Example**

This shows an example.



**How to ...**

This shows a link to a video for help and guidance.

### 1.1.3 Legal information and disclaimer

DEIF takes no responsibility for installation or operation of the generator set or switchgear. If there is any doubt about how to install or operate the engine/generator or switchgear controlled by the Multi-line 2 unit, the company responsible for the installation or the operation of the equipment must be contacted.

**NOTE** The Multi-line 2 unit is not to be opened by unauthorised personnel. If opened anyway, the warranty will be lost.

### **Disclaimer**

DEIF A/S reserves the right to change any of the contents of this document without prior notice.

The English version of this document always contains the most recent and up-to-date information about the product. DEIF does not take responsibility for the accuracy of translations, and translations might not be updated at the same time as the English document. If there is a discrepancy, the English version prevails.

## **1.1.4 Safety during installation and operation**

When you install and operate the equipment, you may have to work with dangerous currents and voltages. The installation must only be carried out by authorised personnel who understand the risks involved in working with electrical equipment.



### **Hazardous live currents and voltages**



Do not touch any terminals, especially the AC measurement inputs and the relay terminals, as this could lead to injury or death.

## **1.1.5 UL/cUL Listed**

The acceptability of the installation is determined as part of the final assembly.

If field-wired in the end application, you must use a physical barrier between the low voltage and higher voltage wiring connections to make sure that the circuits are separated.

## **1.1.6 Current transformer danger**



### **Electrical shock and arc flash**



Risk of burns and electrical shock from high voltage.

Short all current transformer secondaries before breaking any current transformer connections to the controller.

## **1.1.7 Electrostatic discharge awareness**

Sufficient care must be taken to protect the terminal against static discharges during the installation. Once the unit is installed and connected, these precautions are no longer necessary.

## **1.1.8 Factory settings**

The controller is delivered pre-programmed from the factory with a set of default settings. These settings are based on typical values and may not be correct for your system. You must therefore check all parameters before using the controller.

## **1.2 About the installation instructions**

### **1.2.1 General purpose**

These Installation Instructions include hardware information, mounting instructions, terminal strip descriptions, I/O lists and wiring descriptions.

The purpose of this document is to give the user important information to be used in the installation of the controller.



## CAUTION



### Installation errors

Read this document before starting to work with the Multi-line 2 unit and the genset to be controlled. Failure to do this could result in human injury or damage to the equipment.

## 1.2.2 Intended users

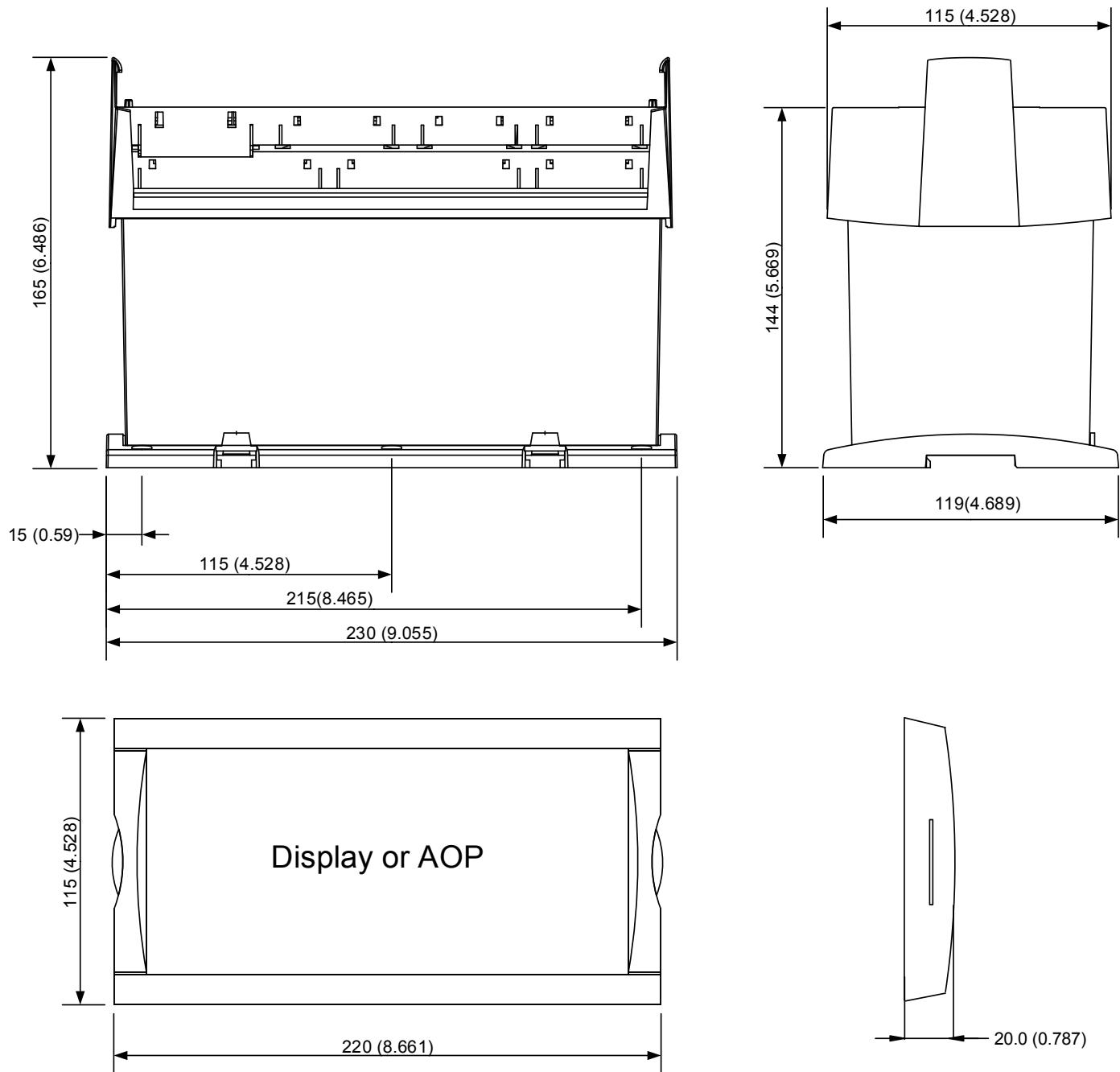
These Installation Instructions are mainly intended for the person responsible for the design and installation. In most cases, this would be a panel builder designer. Naturally, other users might also find useful information in the document.

## 1.2.3 Drawings

See [www.deif.com](http://www.deif.com) for the most recent 3D-files, drawings, E-drawings and E-plans.

## 2. Mounting

### 2.1 Dimensions



**NOTE** Dimensions are given in mm (inches).

### 2.2 Tightening torques

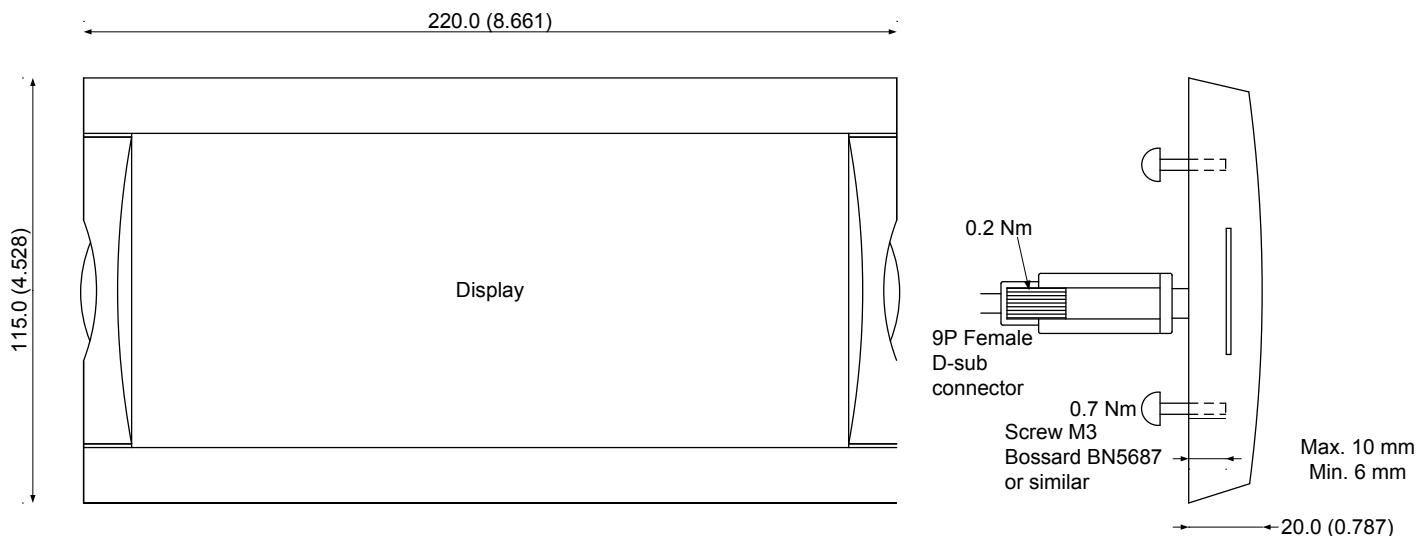
Controller: 1.5 Nm for the six M4 screws (countersunk screws are not to be used)

Plug connections (terminals): 0.5 Nm, 4.4 lb-in

DU-2/AOP-1/AOP-2 (see diagram below)

Panel door mounting: 0.7 Nm, 6.2 lb-in

D-sub screw:	0.2 Nm, 1.8 lb-in
DC-DC converter terminals:	0.5 Nm, 4.4 lb-in



## 2.3 Mounting of the equipment

The controller is designed for mounting inside the panel. The DU-2 display can be installed on the panel door and connected to the controller with a display cable.

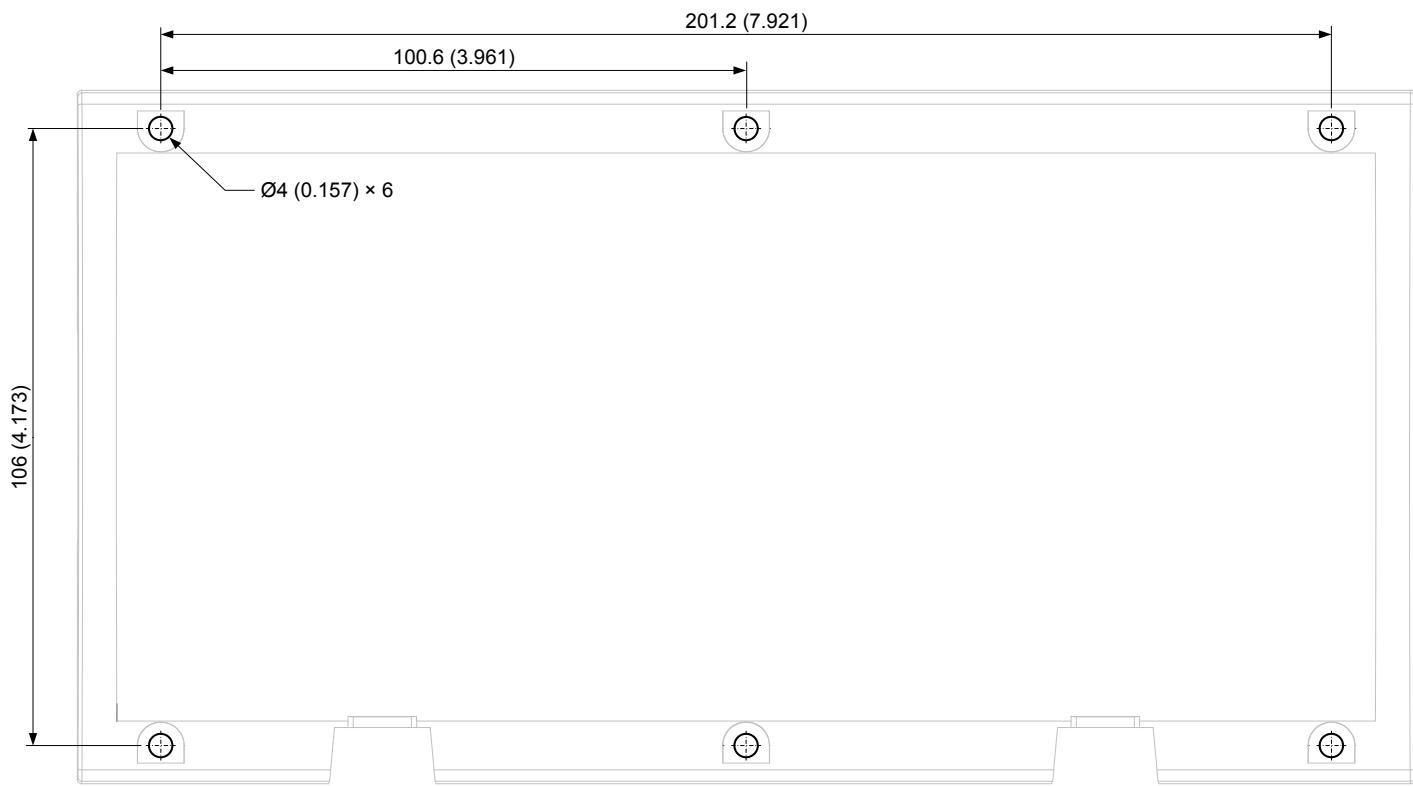
### 2.3.1 Controller mounting

The controller can be mounted:

1. With screws to the rear side of the cabinet. Six screw holes are available for this.
2. Directly on a DIN rail.

**NOTE** DEIF recommends using the screw hole fastening.

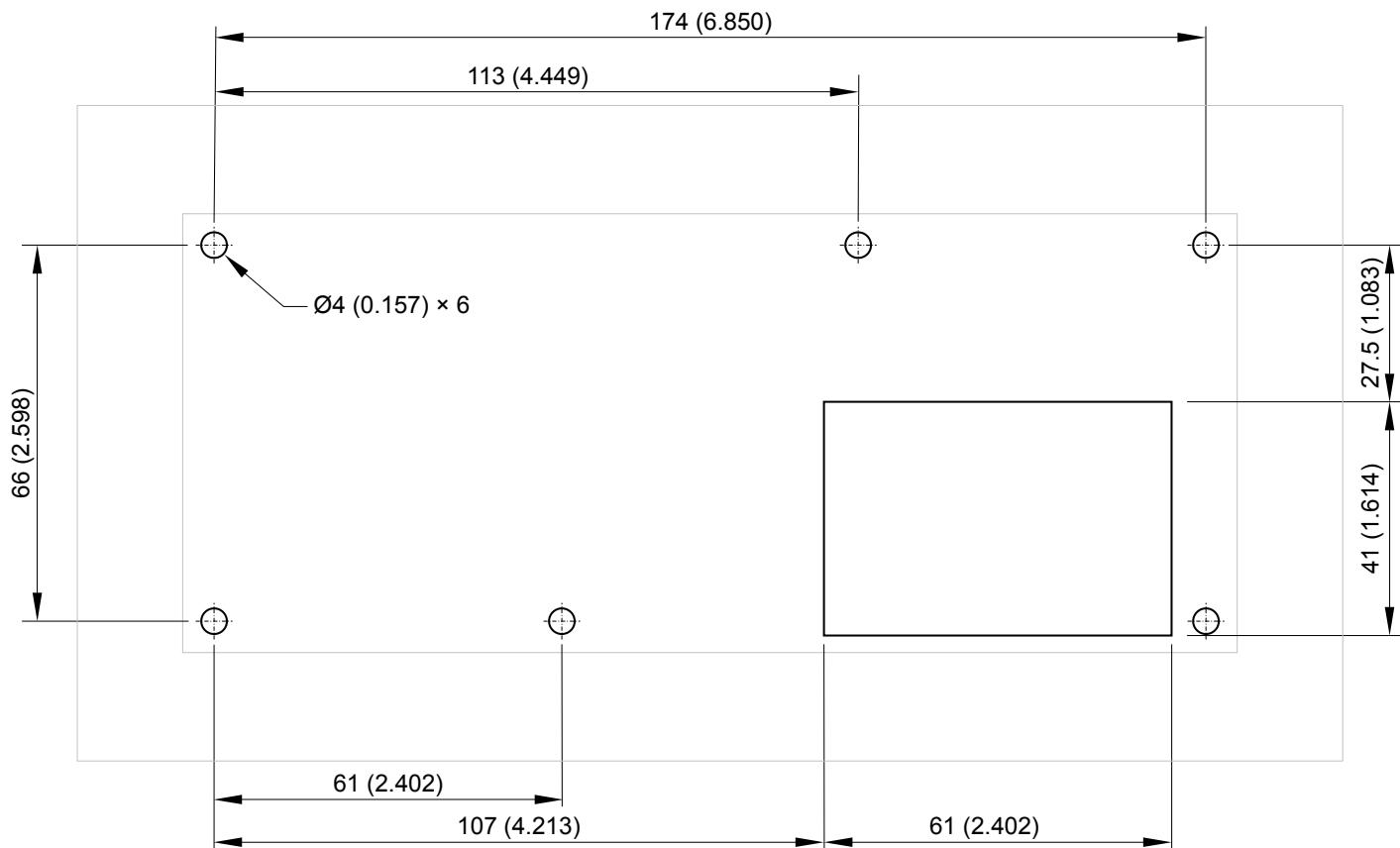
### 2.3.2 Controller mounting drilling diagram



**NOTE** Measurements are in mm (inches).

### 2.3.3 DU-2/AOP display panel cutout

Cut and drill the panel door for the DU-2/AOP according to the diagram below.

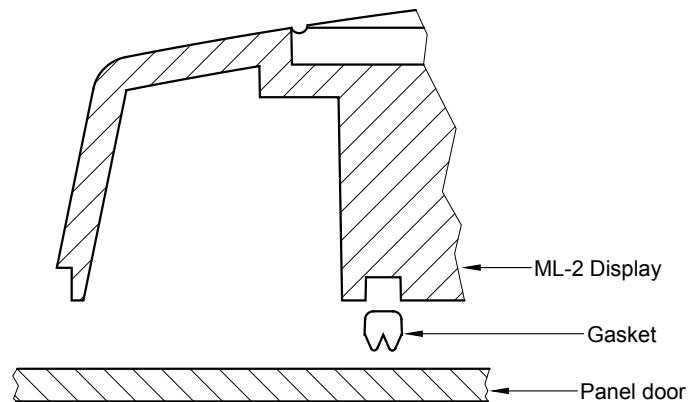


**NOTE** Dimensions are in mm (inches).

### 2.3.4 Mounting of DU-2/AOP gasket (option L1)

It is important to mount the gasket correctly to have an IP65 seal. You must use all six DU-2 or AOP screws to ensure IP65.

Mount the gasket as shown below.



### 3. Hardware

#### 3.1 Board slot positions

The controller housing is divided into board slot positions. This means that the controller consists of a number of printed circuit boards (PCB) mounted in numbered slots. The green terminal blocks are then mounted in the PCBs. Some of these board slots are standard and some are intended for options. The board slot positions are arranged as shown below.

**NOTE** Only the controller hardware options are included in the table. The software options are listed in the PC utility software, and can also be seen in the data sheet.

Slot type	Hardware option	Slot 1	Slot 3	Slot 5	Slot 7
Terminals		1-28	37-64	73-89	98-124, A1-A3, B1-B3
Power supply	Standard	●			
AC measurements	Standard			●	
Engine interface	Standard/M4				●
Power management (software option G5)	Standard				●
I/O extension/load sharing*	M12		●		

Slot type	Hardware option	Slot 2	Slot 4	Slot 6	Slot 8
Terminals		29-36	65-72	90-97	126-133
Analogue transducer outputs	F1			●	
Combination outputs	EF5/EF6		●		
Serial communication	H2/H3/H9	●			
Engine communication	H6/H13				●
CAN bus communication for: Engine communication, DVC, external I/O, CANshare, PMS lite, and/or extended power management**	H12.2/H12.8***	●			●
I/O extension cards	M13.2/M14.2	●			
I/O extension cards	M13.6/M14.6/M15.6/M16.6			●	
I/O extension cards	M13.8/M14.8/M15.8/M16.8				●

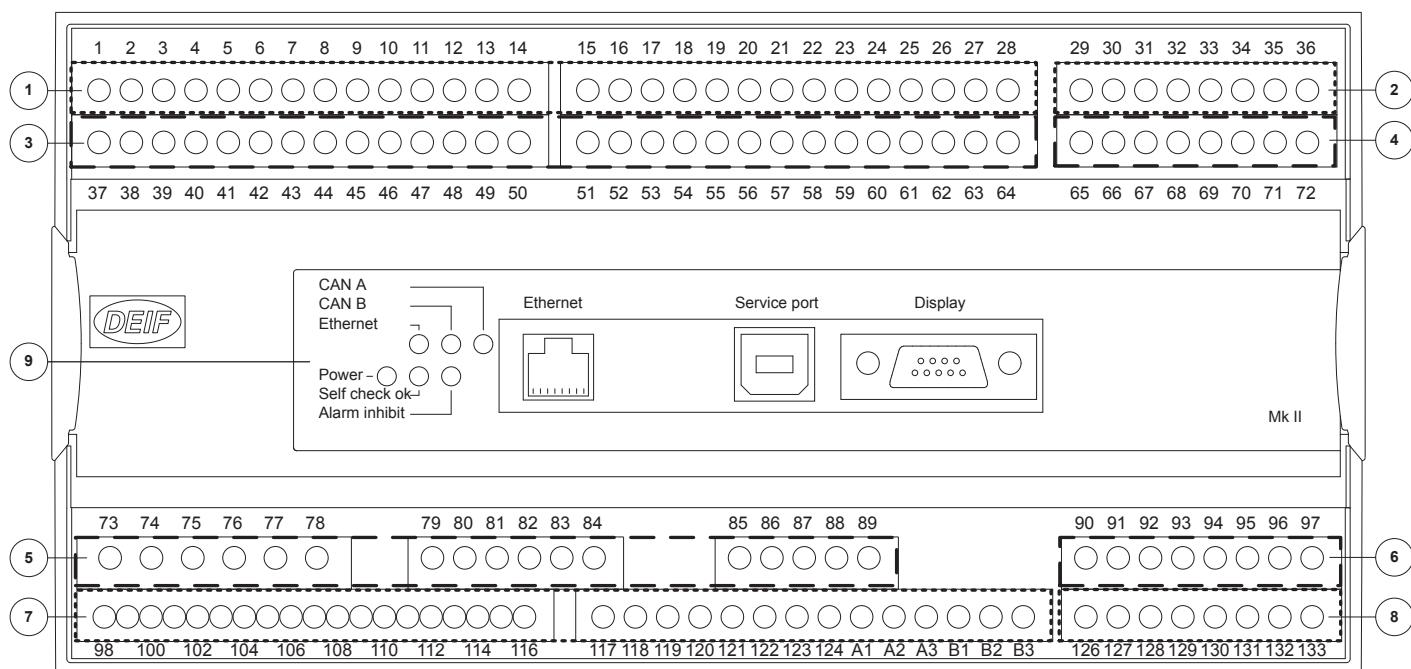
**NOTE** \* Analogue load sharing (option G3) is standard when option M12 is installed.

**NOTE** \*\* The CIOs and IOMs can be connected in series with the engine control unit (ECU) or DVC communication on the CAN line. The group controller uses H12.2 or H12.8 for extended power management CAN communication.

**NOTE** \*\*\* Select either H12.2 or H12.8 (not both).

## 3.2 Controller top side overview

An overview of the terminals is presented below. The slot positions are as follows:



①

These numbers are the slot numbers.

Slot	Terminals	Function
1	1-28	Power supply (standard)
2	29-36	Communication and I/O extensions
3	37-64	In-/outputs/load sharing
4	65-72	Governor, AVR, in-/outputs (standard)
5	73-89	AC measuring (standard)
6	90-97	In-/outputs
7	98-124, A1-A3, B1-B3	Engine I/F (standard)
8	126-133	Engine communication, in-/outputs
9	-	Interfaces and LEDs

### 3.3 Terminal strip overviews

### **3.3.1 Genset controller**

Configurable	72					133		
Configurable	71	Relay 71				132		
Configurable	70					131		
Configurable	69	Relay 69				130		
GOV DOWN/Configurable	68					129		
Configurable	67	Relay 67				128		
GOV UP/Configurable	66					127		
Configurable	65	Relay 65	Slot #4	Slot #8		126		
Configurable	64			Slot #3		B3	CAN L	CAN bus
Configurable	63	Relay 63				B2	GND	Interface B
Configurable	62					B1	CAN H	Power management
Configurable	61	Relay 61				A3	CAN L	CAN bus
Configurable	60					A2	GND	Interface A
Configurable	59	Relay 59				A1	CAN H	Power management
Configurable	58					124		Stop coil
Configurable	57	Relay 57				123		
Common for 43-55	56					122		Crank (Starter)
Configurable	55					121		
Configurable	54					120		Start prepare
Configurable	53					119		Run coil
Configurable	52					118		Emergency stop
Configurable	51					117		Configurable
Configurable	50					116		Configurable
Configurable	49					115		Configurable
Configurable	48					114		Configurable
Configurable	47					113		Configurable
Configurable	46					112		Configurable
Configurable	45					111		Common for 112-117
Configurable	44					110	C	
Configurable	43					109	B	Multi-input 108
Ext. PF/VAr/V set point	42					108	A	
Common for 40/42	41					107	C	
Ext. kW/Hz set point	40					106	B	Multi-input 105
Reactive (Q) load sharing	39					105	A	
Common for 37/39	38					104	C	
Active (P) load sharing	37					103	B	Multi-input 102
						102	A	
						101	GND	MPU input/
						100	Input	Configurable
						99	(-)	Common for 118
						98	(+)	8-36 V DC

**NOTE** The hardware shown in slot #3 is option M12. For details, see the option manual.

### **3.3.2 Mains controller**

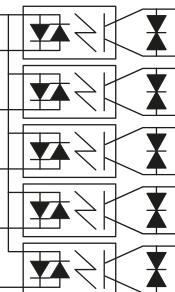
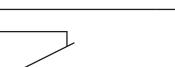
	36					97	
	35					96	
	34					95	
Reserved for options, see Data sheet.	33					94	
	32					93	
	31					92	
	30					91	
	29			Slot #2	Slot #6	90	
Common for 23-27	28			Slot #1	Slot #5		
TB Closed/Configurable	27						
TB Open/Configurable	26						
MB Closed/Configurable	25						
MB Open/Configurable	24						
Configurable	23						
Common for 20/21	22						
kVArh pulse/Relay 21	21						
kWh pulse/Relay 20	20						
Close Tie Breaker/ Configurable	19					89	L3
	18					88	Neutral
	17					87	L2
Open Tie Breaker/ Configurable	16					86	
	15					85	L1
	14					84	Neutral
Close Mains Breaker/ Configurable	13					83	L3
	12					82	
	11					81	L2
Open Mains Breaker/ Configurable	10					80	
	9					79	L1
	8					78	S2 (I) L3 AC current
Alarm horn/ Configurable	7					77	S1 (k) L3 AC current
	6					76	S2 (I) L2 AC current
	5					75	S1 (k) L2 AC current
Status relay	4					74	S2 (I) L1 AC current
	3					73	S1 (k) L1 AC current
DC power supply 8-36 V DC	(-)	2					
	(+)	1					
							Reserved for options, see Data sheet.

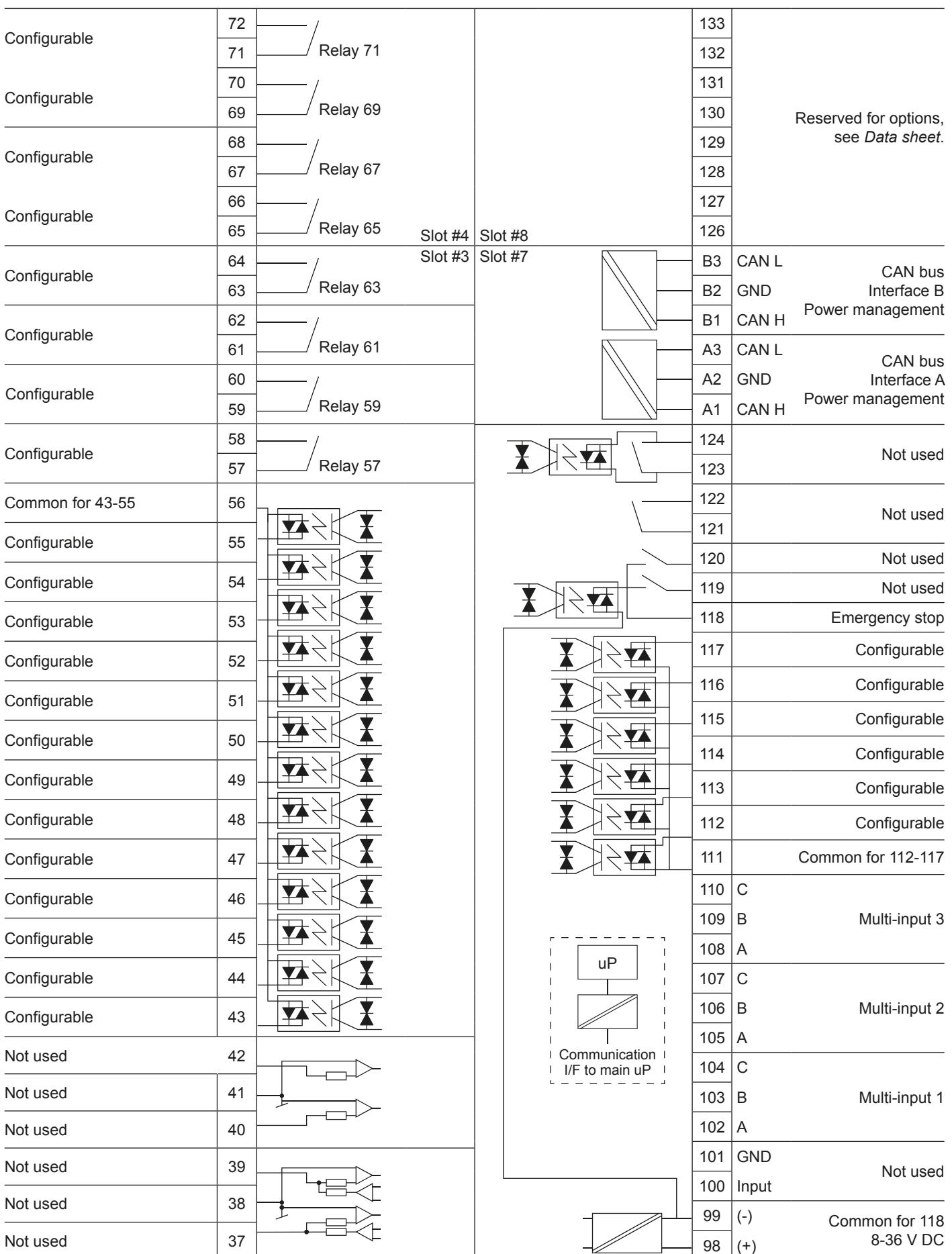
Configurable	72					133		
	71	Relay 71				132		
Configurable	70					131		
	69	Relay 69				130		
Configurable	68					129		
	67	Relay 67				128		
Configurable	66					127		
	65	Relay 65	Slot #4	Slot #8		126		
Configurable	64			Slot #3	Slot #7	B3	CAN L	CAN bus
	63	Relay 63				B2	GND	Interface A
Configurable	62					B1	CAN H	Power management
	61	Relay 61				A3	CAN L	CAN bus
Configurable	60					A2	GND	Interface B
	59	Relay 59				A1	CAN H	Power management
Configurable	58					124		Not used
	57	Relay 57				123		
Common for 43-55	56					122		Not used
Configurable	55					121		
Configurable	54					120		Not used
Configurable	53					119		Not used
Configurable	52					118		Emergency stop
Configurable	51					117		Configurable
Configurable	50					116		Configurable
Configurable	49					115		Configurable
Configurable	48					114		Configurable
Configurable	47					113		Configurable
Configurable	46					112		Configurable
Configurable	45					111		Common for 112-117
Configurable	44					110	C	
Configurable	43					109	B	Multi-input 3
Ext. PF/VAr/V set point	42					108	A	
Common for 40/42	41					107	C	
Ext. kW/Hz set point	40					106	B	Multi-input 2
Not used	39					105	A	
Not used	38					104	C	
Not used	37					103	B	Multi-input 1
						102	A	
						101	GND	
						100	Input	Not used
						99	(-)	Common for 118
						98	(+)	8-36 V DC

The diagram illustrates the internal connections of the board. It shows the physical layout of the board with various components like relays, CAN bus interface, power management, and logic gates. The connections are color-coded and labeled with component numbers and connection points.

**NOTE** The hardware shown in slot #3 is option M12. For details, see the option manual.

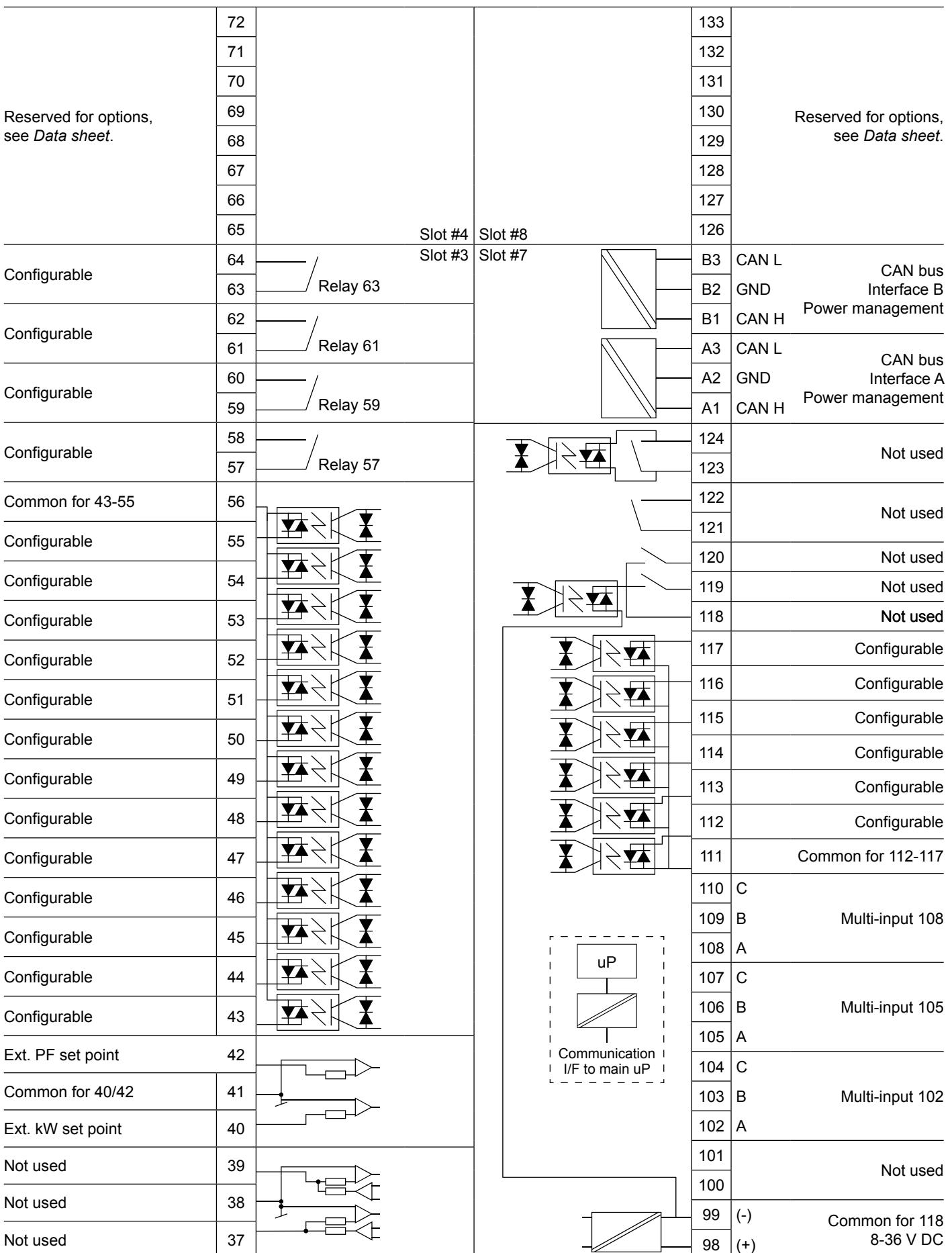
### 3.3.3 BTB controller

Reserved for options, see <i>Data sheet</i> .	36			97	Reserved for options, see <i>Data sheet</i> .
	35			96	
	34			95	
	33			94	
	32			93	
	31			92	
	30			91	
	29			90	
Common for 23-27	28	Slot #2	Slot #6	Slot #5	
BTB Closed/Configurable	27				
BTB Open/Configurable	26				
Configurable	25				
Configurable	24				
Configurable	23				
Common for 20/21	22				
kVArh pulse/Relay 21	21				
kWh pulse/Relay 20	20				
Close Bus Tie Breaker/ Configurable	19				
	18		Relay 17		
	17				
Open Bus Tie Breaker/ Configurable	16				
	15		Relay 14		
	14				
Configurable	13		Relay 11		
	12				
	11				
Configurable	10		Relay 08		
	9				
	8				
Alarm horn/ Configurable	7		Relay 05		
	6				
	5				
Status relay	4		Status relay		
	3				
DC power supply 8-36 V DC	(-)	2			
	(+)	1			
					BUSBAR A VOLTAGE
					BUSBAR B VOLTAGE
					L1
					L2
					L3
					Neutral
					S1 (k)
					S2 (l)
					L1
					L2
					L3
					Neutral

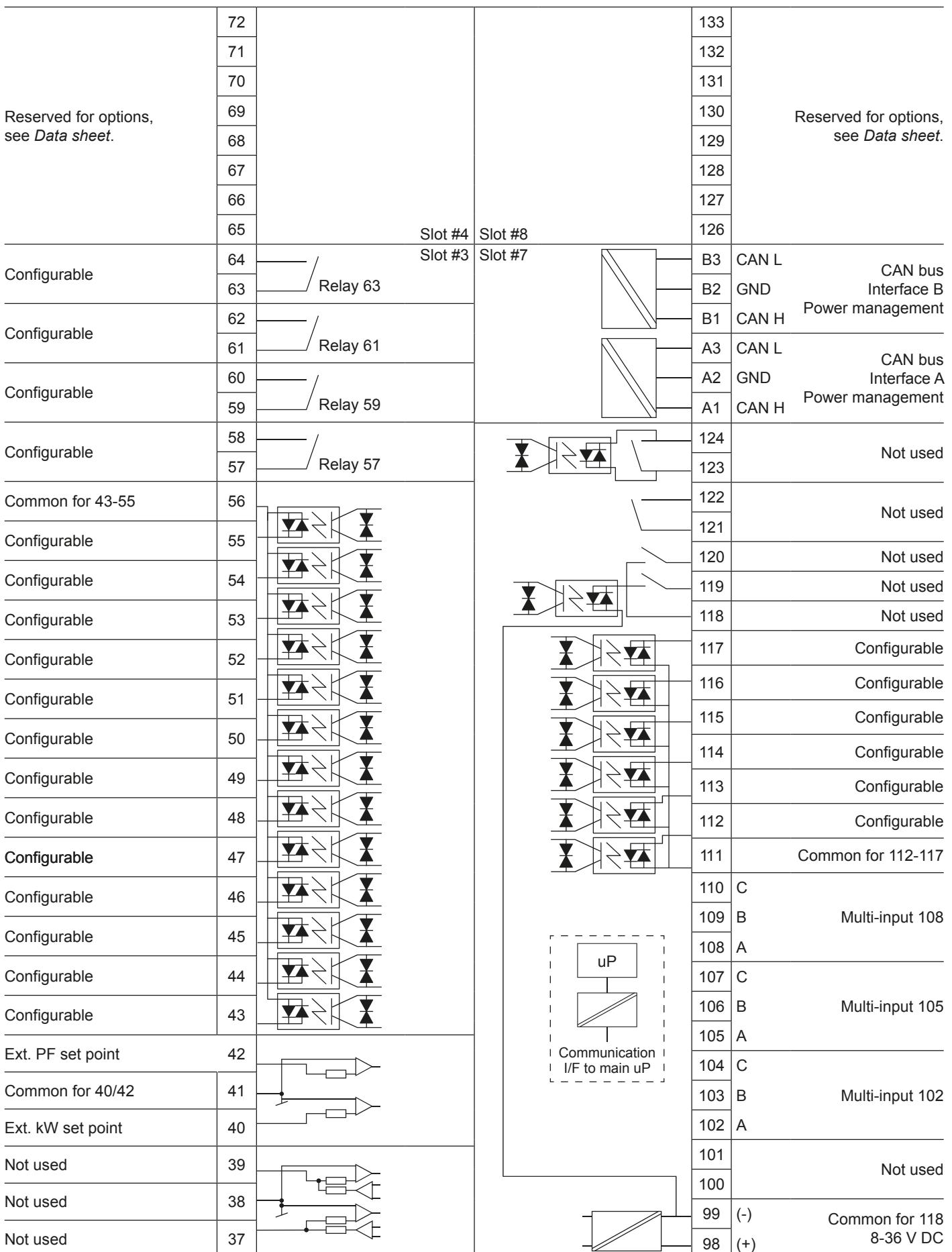


**NOTE** The hardware shown in slot #3 is option M12. For details, see the option manual.

### 3.3.4 Group controller



### **3.3.5 Plant controller**



### 3.4 Input/output lists

The I/O lists use these abbreviations for the relay outputs:

- NO:** Normally Open
- NC:** Normally Closed
- NE:** Normally Energised
- ND:** Normally De-energised
- Com.:** Common terminal

## 3.5 Slot 1

### 3.5.1 Power supply - Genset controller

Term.	Function	Technical data	Description
1	+12/24 V DC	12/24 V DC +/-30 %	Power supply
2	0 V DC		
3	NO	Status relay 24 V DC/1 A	Normally open relay, processor/power supply status supervision
4	Com.		
5	NO		
6	Com.	Relay 05 250 V AC/8 A	Central alarm HORN/configurable
7	NC		
8	NO		
9	Com.	Relay 08 250 V AC/8 A	Open mains breaker/configurable
10	NC		
11	NO		
12	Com.	Relay 11 250 V AC/8 A	Close mains breaker (synchronising)/configurable
13	NC		
14	NO		
15	Com.	Relay 14 250 V AC/8 A	Open generator breaker
16	NC		
17	NO		
18	Com.	Relay 17 250 V AC/8 A	Close generator breaker (synchronising)
19	NC		
20	Open collector 1	Transistor output/Relay 20 36 V DC, 10 mA	Pulse output 1, kWh counter/configurable
21	Open collector 2	Transistor output/Relay 21 36 V DC, 10 mA	Pulse output 2, kvarh counter/configurable
22	Com.	Common	Common terminal for terminals 20 and 21
23	Digital input 23	Optocoupler	Configurable
24	Digital input 24	Optocoupler	Mains breaker open/configurable
25	Digital input 25	Optocoupler	Mains breaker closed/configurable
26	Digital input 26	Optocoupler	Generator breaker open
27	Digital input 27	Optocoupler	Generator breaker closed
28	Com.	Common	Common for terminals 23 to 27

### 3.5.2 Power supply - Mains controller

Term.	Function	Technical data	Description
1	+12/24 V DC	12/24 V DC +/-30 %	Power supply
2	0 V DC		
3	NO	Status relay 24 V DC/1 A	Normally open relay, processor/power supply status supervision
4	Com.		

Term.	Function	Technical data	Description
5	NO		
6	Com.	Relay 05 250 V AC/8 A	Central alarm HORN/configurable
7	NC		
8	NO		
9	Com.	Relay 08 250V AC/8 A	Open mains breaker/configurable
10	NC		
11	NO		
12	Com.	Relay 11 250 V AC/8 A	Close mains breaker (synchronising)/configurable
13	NC		
14	NO		
15	Com.	Relay 14 250 V AC/8 A	Open tie breaker/configurable
16	NC		
17	NO		
18	Com.	Relay 17 250 V AC/8 A	Close tie breaker (synchronising)/configurable
19	NC		
20	Open collector 1	Transistor output/Relay 20 36 V DC, 10 mA	Pulse output 1, kWh counter/configurable
21	Open collector 2	Transistor output/Relay 21 36 V DC, 10 mA	Pulse output 2, kvarh counter/configurable
22	Com.	Common	Common terminal for terminals 20 and 21
23	Digital input 23	Optocoupler	Configurable
24	Digital input 24	Optocoupler	Mains breaker open/configurable
25	Digital input 25	Optocoupler	Mains breaker closed/configurable
26	Digital input 26	Optocoupler	Tie breaker open/configurable
27	Digital input 27	Optocoupler	Tie breaker closed/configurable
28	Com.	Common	Common for terminals 23 to 27

### 3.5.3 Power supply - BTB controller

Term.	Function	Technical data	Description
1	+12/24 V DC	12/24 V DC +/-30 %	Power supply
2	0 V DC		
3	NO	Status relay 24 V DC/1 A	Normally open relay, processor/power supply status supervision
4	Com.		
5	NO		
6	Com.	Relay 05 250 V AC/8 A	Central alarm HORN/configurable
7	NC		
8	NO		
9	Com.	Relay 08 250 V AC/8 A	Configurable
10	NC		

Term.	Function	Technical data	Description
11	NO		
12	Com.	Relay 11 250 V AC/8 A	Configurable
13	NC		
14	NO		
15	Com.	Relay 14 250 V AC/8 A	Open bus tie breaker
16	NC		
17	NO		
18	Com.	Relay 17 250 V AC/8 A	Close bus tie breaker (synchronising)
19	NC		
20	Open collector 1	Transistor output/Relay 20 36 V DC, 10 mA	Configurable
21	Open collector 2	Transistor output/Relay 21 36 V DC, 10 mA	Configurable
22	Com.	Common	Common terminal for terminals 20 and 21
23	Digital input 23	Optocoupler	Configurable
24	Digital input 24	Optocoupler	Configurable
25	Digital input 25	Optocoupler	Configurable
26	Digital input 26	Optocoupler	Configurable
27	Digital input 27	Optocoupler	Configurable
28	Com.	Common	Common for terminals 23 to 27

### 3.5.4 Power supply - Group controller

Term.	Function	Technical data	Description
1	+12/24 V DC	12/24 V DC +/-30 %	Power supply
2	0 V DC		
3	NO		
4	Com.	Status relay 24 V DC/1 A	Normally open relay, processor/power supply status supervision
5	NO		
6	Com.	Relay 05 250 V AC/8 A	Central alarm HORN/configurable
7	NC		
8	NO		
9	Com.	Relay 08 250 V AC/8 A	Configurable
10	NC		
11	NO		
12	Com.	Relay 11 250 V AC/8 A	Configurable
13	NC		
14	NO		
15	Com.	Relay 14 250 V AC/8 A	Open tie breaker
16	NC		

Term.	Function	Technical data	Description
17	NO		
18	Com.	Relay 17 250 V AC/8 A	Close tie breaker (synchronising)
19	NC		
20	Open collector 1	Transistor output/Relay 20 36 V DC, 10 mA	Configurable
21	Open collector 2	Transistor output/Relay 21 36 V DC, 10 mA	Configurable
22	Com.	Common	Common terminal for terminals 20 and 21
23	Digital input 23	Optocoupler	Configurable
24	Digital input 24	Optocoupler	Configurable
25	Digital input 25	Optocoupler	Configurable
26	Digital input 26	Optocoupler	Tie breaker open
27	Digital input 27	Optocoupler	Tie breaker closed/configurable
28	Com.	Common	Common for terminals 23 to 27

### 3.5.5 Power supply - Plant controller

Term.	Function	Technical data	Description
1	+12/24 V DC	12/24 V DC +/-30 %	Power supply
2	0 V DC		
3	NO	Status relay 24 V DC/1 A	Normally open relay, processor/power supply status supervision
4	Com.		
5	NO		
6	Com.	Relay 05 250 V AC/8 A	Central alarm HORN/configurable
7	NC		
8	NO		
9	Com.	Relay 08 250 V AC/8 A	Open mains breaker/configurable
10	NC		
11	NO		
12	Com.	Relay 11 250 V AC/8 A	Close mains breaker (synchronising)/configurable
13	NC		
14	NO		
15	Com.	Relay 14 250 V AC/8 A	Configurable
16	NC		
17	NO		
18	Com.	Relay 17 250 V AC/8 A	Configurable
19	NC		
20	Open collector 1	Transistor output/Relay 20 36 V DC, 10 mA	Pulse output 1, kWh counter/configurable
21	Open collector 2	Transistor output/Relay 21 36 V DC, 10 mA	Pulse output 2, kvarh counter/configurable

<b>Term.</b>	<b>Function</b>	<b>Technical data</b>	<b>Description</b>
22	Com.	Common	Common terminal for terminals 20 and 21
23	Digital input 23	Optocoupler	Configurable
24	Digital input 24	Optocoupler	Mains breaker open/Configurable
25	Digital input 25	Optocoupler	Mains breaker closed/configurable
26	Digital input 26	Optocoupler	Configurable
27	Digital input 27	Optocoupler	Configurable
28	Com.	Common	Common for terminals 23 to 27

## 3.6 Slot 2

### 3.6.1 Serial communication (option H)

#### Modbus RTU, RS-485 (option H2)

Term.	Function	Description
29	DATA + (A)	Modbus RTU, RS-485
30	GND	
31	DATA - (B)	
32	Not used	
33	DATA + (A)	
34	Not used	
35	DATA - (B)	
36	Not used	

The serial communication line should be terminated between DATA + and DATA - with a resistor equal to the cable impedance. The terminals 29/33 and 31/35 are internally connected.

**NOTE** Never connect the GND terminal 30 to earth. Only connect it to a third wire in the communication cable!

#### Modbus RTU, RS-232 (option H9)

Term.	Function	Description
29	Not used	Modbus RTU, RS-232
30	GND	
31	Not used	
32	TxD	
33	Not used	
34	RxD	
35	Not used	
36	Not used	

**NOTE** Never connect the GND terminal 30 to earth. Only connect it to a third wire in the communication cable!

#### Profibus (option H3)

Term.	Function	Description
29	DATA + (B)	Pin 3 on 9-pole D-sub connector Pin 5 on 9-pole D-sub connector Pin 8 on 9-pole D-sub connector
30	GND	
31	DATA - (A)	
32	DATA + (B)	
33	GND	
34	DATA - (A)	
35	Not used	
36	Not used	

**NOTE** Never connect the GND terminal 30 to earth. Only connect it to a third wire in the communication cable!

### 3.6.2 Dual CAN (option H12.2)

Term.	Function	Description
29	CAN-H	The H12 dual CAN bus can be used for: <ul style="list-style-type: none"><li>• Engine interface communication</li><li>• DVC 550/350 communication</li><li>• External I/O module (CIO 116/208/308 and/or IOM 220/230)</li><li>• CANshare</li></ul>
30	CAN-GND	
31	CAN-L	
32	CAN-H	
33	CAN-GND	
34	CAN-L	
35	Not used	The terminals are configurable: Terminals 29-31: CAN C Terminals 32-34: CAN D
36	Not used	

### 3.6.3 7 digital inputs (option M13.2)

Term.	Function	Technical data	Description
29	Digital input 29	Optocoupler	Configurable
30	Digital input 30	Optocoupler	Configurable
31	Digital input 31	Optocoupler	Configurable
32	Digital input 32	Optocoupler	Configurable
33	Digital input 33	Optocoupler	Configurable
34	Digital input 34	Optocoupler	Configurable
35	Digital input 35	Optocoupler	Configurable
36	Com.	Optocoupler	Common for terminals 29 to 35

### 3.6.4 Relay outputs (option M14.2)

Term.	Function	Technical data	Description
29	NE/ND	Relay 29 250 V AC/5 A	Configurable
30	Com.		
31	NE/ND	Relay 31 250 V AC/5 A	Configurable
32	Com.		
33	NE/ND	Relay 33 250 V AC/5 A	Configurable
34	Com.		
35	NE/ND	Relay 35 250 V AC/5 A	Configurable
36	Com.		

## 3.7 Slot 3

### 3.7.1 Load sharing, 13 digital inputs, 4 relay outputs (option M12)

Term.	Function	Technical data	Description
37	-5 to 0 to 5 V DC	Analogue load sharing	Active load sharing line
38	Com.	Common	Common for load sharing lines
39	-5 to 0 to 5 V DC	Analogue load sharing	Reactive load sharing
40	-10/+10 V DC	Analogue input	f/P set point
41	Com.	Common	Common for 40/42
42	-10/+10 V DC	Analogue input	U/Q set point
43	Digital input	Optocoupler	Configurable
44	Digital input	Optocoupler	Configurable
45	Digital input	Optocoupler	Configurable
46	Digital input	Optocoupler	Configurable
47	Digital input	Optocoupler	Configurable
48	Digital input	Optocoupler	Configurable
49	Digital input	Optocoupler	Configurable
50	Digital input	Optocoupler	Configurable
51	Digital input	Optocoupler	Configurable
52	Digital input	Optocoupler	Configurable
53	Digital input	Optocoupler	Configurable
54	Digital input	Optocoupler	Configurable
55	Digital input	Optocoupler	Configurable
56	Com.	Common	Common for terminals 43 to 55
57	NE/ND	Relay 57 250 V AC/5 A	Configurable
58	Com.		
59	NE/ND	Relay 59 250 V AC/5 A	Configurable
60	Com.		
61	NE/ND	Relay 61 250 V AC/5 A	Configurable
62	Com.		
63	NE/ND	Relay 63 250 V AC/5 A	Configurable
64	Com.		

## 3.8 Slot 4

### 3.8.1 Relay outputs (option M14.4, standard)

Term.	Function	Technical data	Description
65	NE/ND	Relay 65 250 V AC/5 A	Generator GOV: Increase frequency/configurable
66	Com.		
67	NE/ND	Relay 67 250 V AC/5 A	Generator GOV: Decrease frequency/configurable
68	Com.		
69	Not used	Relay 69 250 V AC/5 A	Configurable
70	Com.		
71	Not used	Relay 71 250 V AC/5 A	Configurable
72	Com.		

### 3.8.2 PWM, relay and analogue outputs for GOV/AVR (option EF5)

Term.	Function	Description
65	+/-25 mA	AVR set point output
66	0	
67	PWM +	PWM speed governor signal
68	PWM -	
69	NO	Relay output for AVR. Raise voltage
70	Com.	
71	NO	Relay output for AVR. Lower voltage
72	Com.	

**NOTE** AVR control requires software option D1. This is included as a standard option in AGC-4 Mk II.

### 3.8.3 PWM and analogue outputs for GOV/AVR (option EF6)

Term.	Function	Description
65	Not used	
66	Not used	
67	0	
68	+/-25 mA	Speed governor, AVR or transducer output 68
69	PWM -	PWM speed governor signal
70	PWM +	
71	0	
72	+/-25 mA	Speed governor, AVR or transducer output 72

**NOTE** Connect PWM - to the engine battery negative and PWM + to the engine control system S-SPD (speed) input (called RATED SPEED on the ADEM controller and PRIMARY THROTTLE on the PEEC controller).

## 3.9 Slot 5

### 3.9.1 AC measuring - Genset controller

Term.	Function	Technical data	Description
73	I L1, s1	Generator current L1	x/1 A or x/5 A input
74	I L1, s2		
75	I L2, s1	Generator current L2	x/1 A or x/5 A input
76	I L2, s2		
77	I L3, s1	Generator current L3	x/1 A or x/5 A input
78	I L3, s2		
79	U L1	Generator voltage L1	Max. 690 V AC phase-phase value
80		Not used	
81	U L2	Generator voltage L2	Max. 690 V AC phase-phase value
82		Not used	
83	U L3	Generator voltage L3	Max. 690 V AC phase-phase value
84	U <sub>NEUTRAL</sub>	Generator voltage neutral	
85	U L1	Mains/bus voltage L1	Max. 690 V AC phase-phase value
86		Not used	
87	U L2	Mains/bus voltage L2	Max. 690 V AC phase-phase value
88	U <sub>NEUTRAL</sub>	Mains/bus voltage neutral	
89	U L3	Mains/bus voltage L3	Max. 690 V AC phase-phase value

### 3.9.2 AC measuring - Mains controller

Term.	Function	Technical data	Description
73	I L1, s1	Mains current L1	x/1 A or x/5 A input
74	I L1, s2		
75	I L2, s1	Mains current L2	x/1 A or x/5 A input
76	I L2, s2		
77	I L3, s1	Mains current L3	x/1 A or x/5 A input
78	I L3, s2		
79	U L1	Mains voltage L1	Max. 690 V AC phase-phase value
80		Not used	
81	U L2	Mains voltage L2	Max. 690 V AC phase-phase value
82		Not used	
83	U L3	Mains voltage L3	Max. 690 V AC phase-phase value
84	U <sub>NEUTRAL</sub>	Mains voltage neutral	
85	U L1	Bus voltage L1	Max. 690 V AC phase-phase value
86		Not used	
87	U L2	Bus voltage L2	Max. 690 V AC phase-phase value

Term.	Function	Technical data	Description
88	U <sub>NEUTRAL</sub>	Bus voltage neutral	
89	U L3	Bus voltage L3	Max. 690 V AC phase-phase value

### 3.9.3 AC measuring - BTB controller

Term.	Function	Technical data	Description
73	I L1, s1	Bus A current L1	x/1 A or x/5 A input
74	I L1, s2		
75	I L2, s1	Bus A current L2	x/1 A or x/5 A input
76	I L2, s2		
77	I L3, s1	Bus A current L3	x/1 A or x/5 A input
78	I L3, s2		
79	U L1	Bus A voltage L1	Max. 690 V AC phase-phase value
80		Not used	
81	U L2	Bus A voltage L2	Max. 690 V AC phase-phase value
82		Not used	
83	U L3	Bus A voltage L3	Max. 690 V AC phase-phase value
84	U <sub>NEUTRAL</sub>	Bus A voltage neutral	
85	U L1	Bus B voltage L1	Max. 690 V AC phase-phase value
86		Not used	
87	U L2	Bus B voltage L2	Max. 690 V AC phase-phase value
88	U <sub>NEUTRAL</sub>	Bus B voltage neutral	
89	U L3	Bus B voltage L3	Max. 690 V AC phase-phase value

### 3.9.4 AC measuring - Group controller

Term.	Function	Technical data	Description
73	I L1, s1	Generator current L1	x/1 A or x/5 A input
74	I L1, s2		
75	I L2, s1	Generator current L2	x/1 A or x/5 A input
76	I L2, s2		
77	I L3, s1	Generator current L3	x/1 A or x/5 A input
78	I L3, s2		
79	U L1	Generator voltage L1	Max. 690 V AC phase-phase value
80		Not used	
81	U L2	Generator voltage L2	Max. 690 V AC phase-phase value
82		Not used	
83	U L3	Generator voltage L3	Max. 690 V AC phase-phase value
84	U <sub>NEUTRAL</sub>	Generator voltage neutral	
85	U L1	BB voltage L1	Max. 690 V AC phase-phase value
86		Not used	

<b>Term.</b>	<b>Function</b>	<b>Technical data</b>	<b>Description</b>
87	U L2	BB voltage L2	Max. 690 V AC phase-phase value
88	U <sub>NEUTRAL</sub>	BB voltage neutral	
89	U L3	BB voltage L3	Max. 690 V AC phase-phase value

### 3.9.5 AC measuring - Plant controller

<b>Term.</b>	<b>Function</b>	<b>Technical data</b>	<b>Description</b>
73	I L1, s1	Mains current L1	x/1 A or x/5 A input
74	I L1, s2		
75	I L2, s1	Mains current L2	x/1 A or x/5 A input
76	I L2, s2		
77	I L3, s1	Mains current L3	x/1 A or x/5 A input
78	I L3, s2		
79	U L1	Mains voltage L1	Max. 690 V AC phase-phase value
80		Not used	
81	U L2	Mains voltage L2	Max. 690 V AC phase-phase value
82		Not used	
83	U L3	Mains voltage L3	Max. 690 V AC phase-phase value
84	U <sub>NEUTRAL</sub>	Mains voltage neutral	
85	U L1	BB voltage L1	Max. 690 V AC phase-phase value
86		Not used	
87	U L2	BB voltage L2	Max. 690 V AC phase-phase value
88	U <sub>NEUTRAL</sub>	BB voltage neutral	
89	U L3	BB voltage L3	Max. 690 V AC phase-phase value

## 3.10 Slot 6

### 3.10.1 7 digital inputs (option M13.6)

Term.	Function	Technical data	Description
90	Com.	Common	Common for terminals 90 to 97
91	Binary input 91	Optocoupler	Configurable
92	Binary input 92	Optocoupler	Configurable
93	Binary input 93	Optocoupler	Configurable
94	Binary input 94	Optocoupler	Configurable
95	Binary input 95	Optocoupler	Configurable
96	Binary input 96	Optocoupler	Configurable
97	Binary input 97	Optocoupler	Configurable

### 3.10.2 4 relay outputs (option M14.6)

Term.	Function	Technical data	Description
90	NE/ND	Relay 90 250 V AC 5 A	Configurable
91	Com.	250 V AC 5 A	
92	NE/ND	Relay 92 250 V AC 5 A	Configurable
93	Com.	250 V AC 5 A	
94	NE/ND	Relay 94 250 V AC 5 A	Configurable
95	Com.	250 V AC 5 A	
96	NE/ND	Relay 96 250 V AC 5 A	Configurable
97	Com.	250 V AC 5 A	

### 3.10.3 4 analogue inputs (option M15.6)

Term.	Function	Technical data	Description
90	Analogue input 91 -	Common	Configurable
91	Analogue input 91 +	4 to 20 mA in	
92	Analogue input 93 -	Common	Configurable
93	Analogue input 93 +	4 to 20 mA in	
94	Analogue input 95 -	Common	Configurable
95	Analogue input 95 +	4 to 20 mA in	
96	Analogue input 97 -	Common	Configurable
97	Analogue input 97 +	4 to 20 mA in	

### 3.10.4 4 multi-inputs (option M16.6)

Term.	Function	Technical data	Description
90	Multi-input 91	Common	Configurable: 4 to 20 mA/0 to 5 V/Pt100
91	Multi-input 91	Analogue in	

Term.	Function	Technical data	Description
92	Multi-input 93	Common	
93	Multi-input 93	Analogue in	Configurable: 4 to 20 mA/0 to 5 V/Pt100
94	Multi-input 95	Common	
95	Multi-input 95	Analogue in	Configurable: 4 to 20 mA/0 to 5 V/Pt100
96	Multi-input 97	Common	
97	Multi-input 97	Analogue in	Configurable: 4 to 20 mA/0 to 5 V/Pt100

### 3.10.5 Analogue outputs for transducer (option F1)

Term.	Function	Description
90	Not used	
91	0	Transducer output
92	0(4) to 20 mA out	
93	Not used	
94	Not used	
95	0	Transducer output
96	0(4) to 20 mA out	
97	Not used	

**NOTE** The option F1 cannot be used for GOV/AVR outputs.

## 3.11 Slot 7

### 3.11.1 Engine interface card - Genset controller

Term.	Function	Technical data	Description
98	+12/24 V DC	12/24 V DC +/-30 %	DC power supply
99	0 V DC		
100	MPU input	2 to 70 V AC/ 10 to 10,000 Hz	Magnetic pickup with wire break
101	MPU GND		
102	A		
103	B		Multi-input 1
104	C	0(4) to 20 mA Digital Pt100 Pt1000	
105	A	RMI	
106	B	0 to 40 V DC	Multi-input 2
107	C		
108	A		
109	B		Multi-input 3
110	C		
111	Com.	Common	Common for terminals 112 to 117
112	Digital input 112	Optocoupler	Configurable
113	Digital input 113	Optocoupler	Configurable
114	Digital input 114	Optocoupler	Configurable
115	Digital input 115	Optocoupler	Configurable
116	Digital input 116	Optocoupler	Configurable
117	Digital input 117	Optocoupler	Configurable
118	Digital input 118	Optocoupler	Emergency stop and common for 119 and 120
119	NO	Relay 24 V DC/5 A	Run coil
120	NO	Relay 24 V DC/5 A	Start prepare
121	Com.	Relay	Crank (starter)
122	NO	250 V AC/5 A	
123	Com.	Relay	Stop coil w/wire failure detection
124	NO	24 V DC/5 A	
A1	CAN-H		
A2	GND		CAN bus interface A Used for option G5: Power management
A3	CAN-L		
B1	CAN-H		
B2	GND		CAN bus interface B Used for option G5: Power management
B3	CAN-L		

### 3.11.2 Engine interface card - Mains/BTB/Group/Plant controller

Term.	Function	Technical data	Description
98	+12/24 V DC	12/24 V DC +/-30 %	DC power supply
99	0 V DC		
100	MPU input	2 to 70 V AC/ 10 to 10,000 Hz	Magnetic pickup
101	MPU GND		
102	A		
103	B		Multi-input 1
104	C	0(4) to 20 mA Digital Pt100 Pt1000 RMI	
105	A	0 to 40 V DC	Multi-input 2
106	B		
107	C		
108	A		
109	B		Multi-input 3
110	C		
111	Com.	Common	Common for terminals 112-117
112	Digital input 112	Optocoupler	Configurable
113	Digital input 113	Optocoupler	Configurable
114	Digital input 114	Optocoupler	Configurable
115	Digital input 115	Optocoupler	Configurable
116	Digital input 116	Optocoupler	Configurable
117	Digital input 117	Optocoupler	Configurable
118	Digital input 118	Optocoupler	Emergency stop and common for 119 and 120
119	NO	Relay 24 V DC/5 A	Not used
120	NO	Relay 24 V DC/5 A	Not used
121	Com.	Relay	
122	NO	250 V AC/5 A	Not used
123	Com.	Relay	
124	NO	24 V DC/5 A	Not used
A1	CAN-H		
A2	GND		CAN bus interface A Used for option G5: Power management
A3	CAN-L		
B1	CAN-H		
B2	GND		CAN bus interface B Used for option G5: Power management
B3	CAN-L		

## 3.12 Slot 8

### 3.12.1 Cummins engine interface communication (option H6)

Term.	Function	Description
126	Not used	Modbus RTU (RS-485)
127	DATA - (B)	
128	Not used	
129	DATA + (A)	
130	Not used	
131	DATA - (B)	
132	GND	
133	DATA + (A)	

### 3.12.2 7 digital inputs (option M13.8)

Term.	Function	Technical data	Description
126	Com.	Common	Common for terminals 127 to 133
127	Digital input 127	Optocoupler	Configurable
128	Digital input 128	Optocoupler	Configurable
129	Digital input 129	Optocoupler	Configurable
130	Digital input 130	Optocoupler	Configurable
131	Digital input 131	Optocoupler	Configurable
132	Digital input 132	Optocoupler	Configurable
133	Digital input 133	Optocoupler	Configurable

### 3.12.3 4 relay outputs (option M14.8)

Term.	Function	Technical data	Description
126	NE/ND	Relay 126 250 V AC/5 A	Configurable
127	Com.		
128	NE/ND	Relay 128 250 V AC/5 A	Configurable
129	Com.		
130	NE/ND	Relay 130 250 V AC/5 A	Configurable
131	Com.		
132	NE/ND	Relay 132 250 V AC/5 A	Configurable
133	Com.		

### 3.12.4 4 analogue inputs (option M15.8)

Term.	Function	Technical data	Description
126	Analogue input 127 -	Common	Configurable
127	Analogue input 127 +	4 to 20 mA in	

Term.	Function	Technical data	Description
128	Analogue input 129 -	Common	
129	Analogue input 129 +	4 to 20 mA in	Configurable
130	Analogue input 131 -	Common	
131	Analogue input 131 +	4 to 20 mA in	Configurable
132	Analogue input 133 -	Common	
133	Analogue input 133 +	4 to 20 mA in	Configurable

### 3.12.5 4 multi-inputs (option M16.8)

Term.	Function	Technical data	Description
126	Multi-input 127	Common	
127	Multi-input 127	Analogue in	Configurable: 4 to 20 mA/0 to 5 V/Pt100
128	Multi-input 129	Common	
129	Multi-input 129	Analogue in	Configurable: 4 to 20 mA/0 to 5 V/Pt100
130	Multi-input 131	Common	
131	Multi-input 131	Analogue in	Configurable: 4 to 20 mA/0 to 5 V/Pt100
132	Multi-input 133	Common	
133	Multi-input 133	Analogue in	Configurable: 4 to 20 mA/0 to 5 V/Pt100

### 3.12.6 Dual CAN (option H12.8)

Term.	Function	Description
126	Not used	The H12 dual CAN bus can be used for:
127	Not used	<ul style="list-style-type: none"> <li>• Engine interface communication</li> <li>• DVC 550/350 communication</li> </ul>
128	CAN-L	<ul style="list-style-type: none"> <li>• External I/O module (CIO 116/208/308 and/or IOM 220/230)</li> <li>• CANshare</li> </ul>
129	GND	
130	CAN-H	<ul style="list-style-type: none"> <li>• PMS lite</li> <li>• Group controller: Extended power management (option G7) communication</li> </ul>
131	CAN-L	
132	GND	
133	CAN-H	<p>The terminals are configurable:            Terminals 128-130: CAN E            Terminals 131-133: CAN F</p>

## 4. Wiring

### 4.1 AC connections

The controller can be wired up in a 1-phase, 2-phase or 3-phase configuration. 3-phase examples are included for each controller type.

**NOTE** Contact the switchboard manufacturer for accurate information about required wiring for the specific application.

#### **Neutral line (N)**

For three phases systems, the neutral line (N) is only required if the system is a three-phase + neutral system. If the distribution system is a three-phase system without neutral, do not connect terminals 84 and 88.

#### **Current transformer grounding**

The current transformers can be grounded using the s1 or s2 connections.

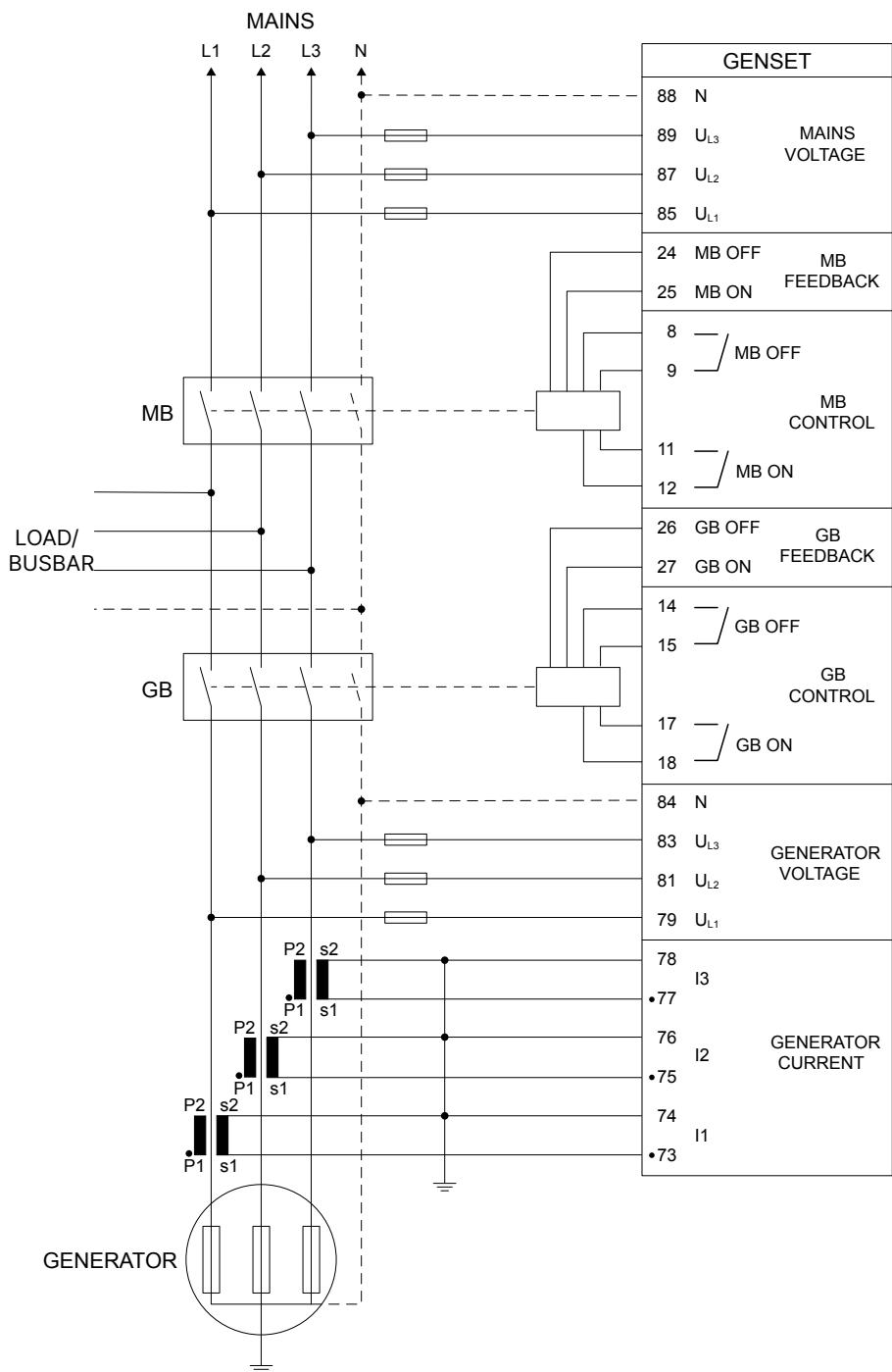
#### **Fuses**

Protect the AC voltage measurement cables with 2 A time-delay fuses.

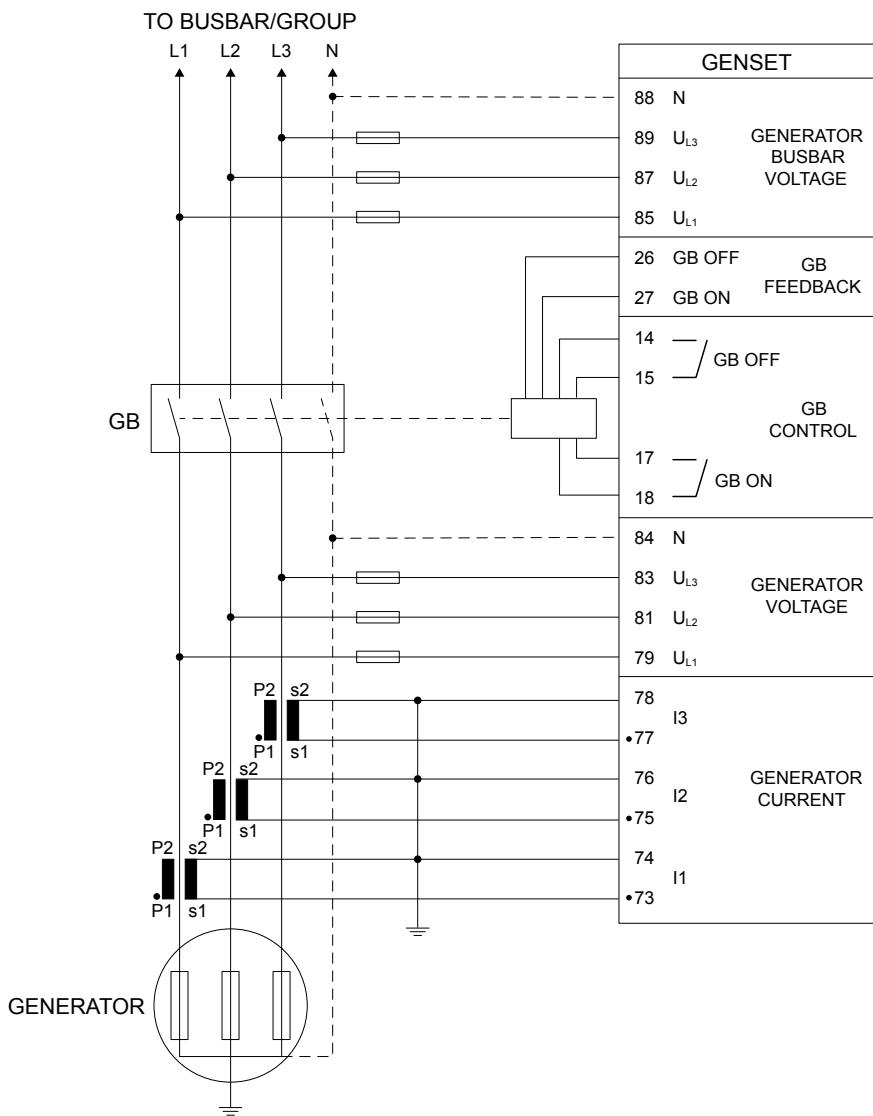
#### **Breaker wiring**

The examples are for pulse breakers. Breaker open/off wiring is not required for a continuous breaker.

#### 4.1.1 Genset controller (stand-alone)

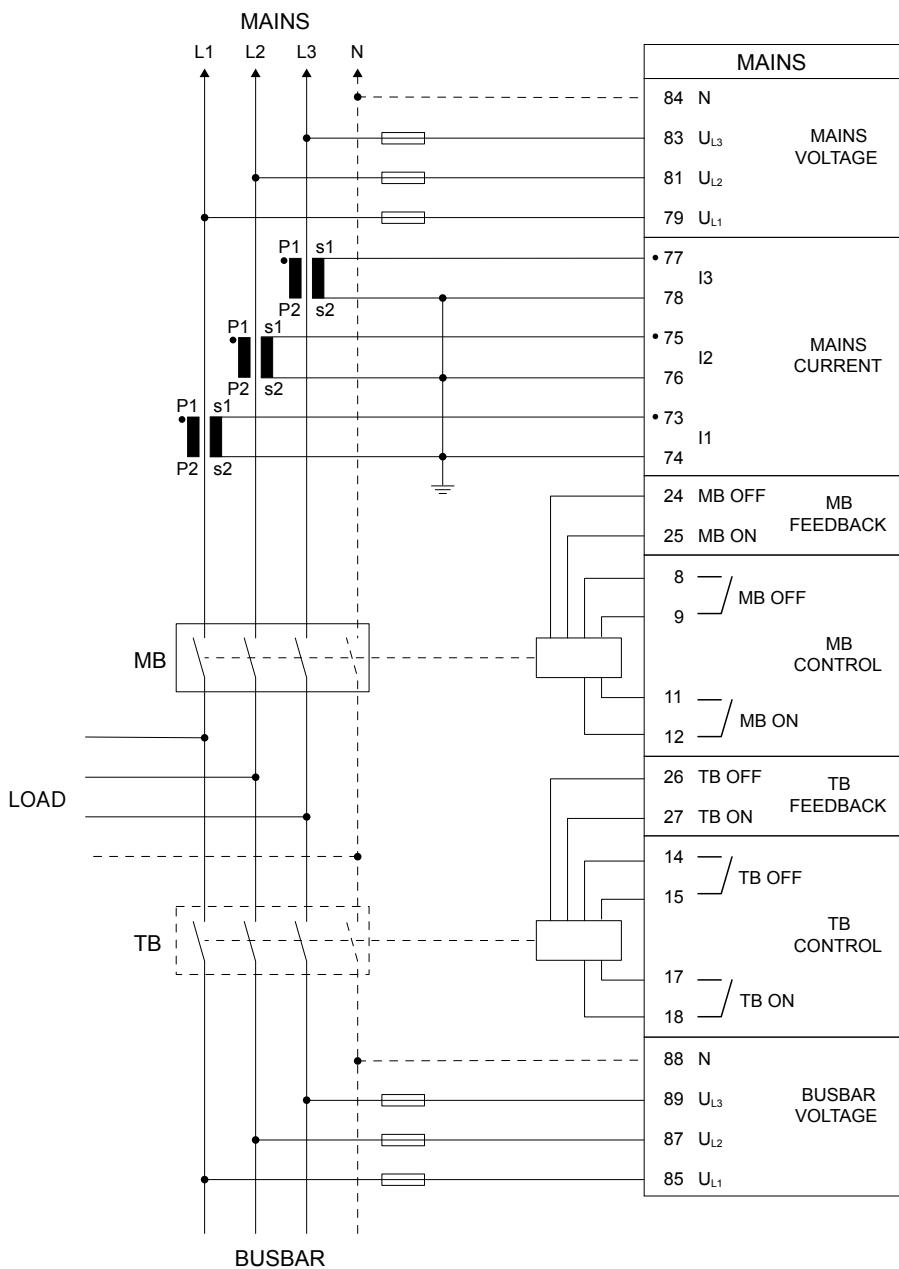


#### 4.1.2 Genset controller (island/power management)

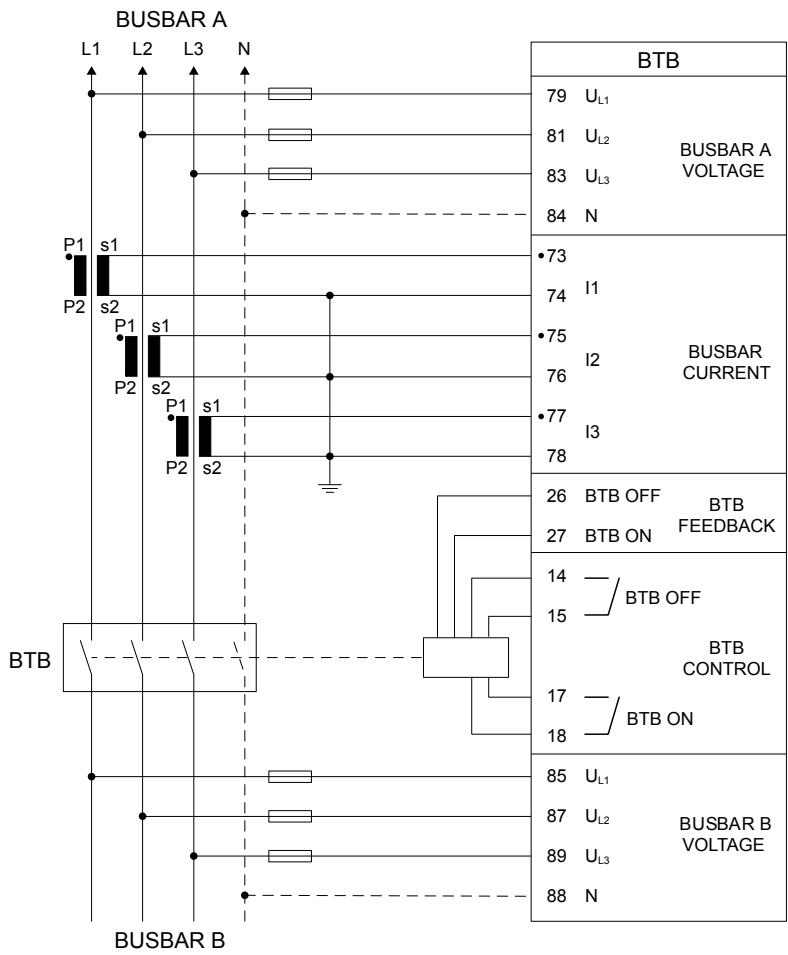


This wiring also applies to genset controllers in CANshare and PMS lite applications.

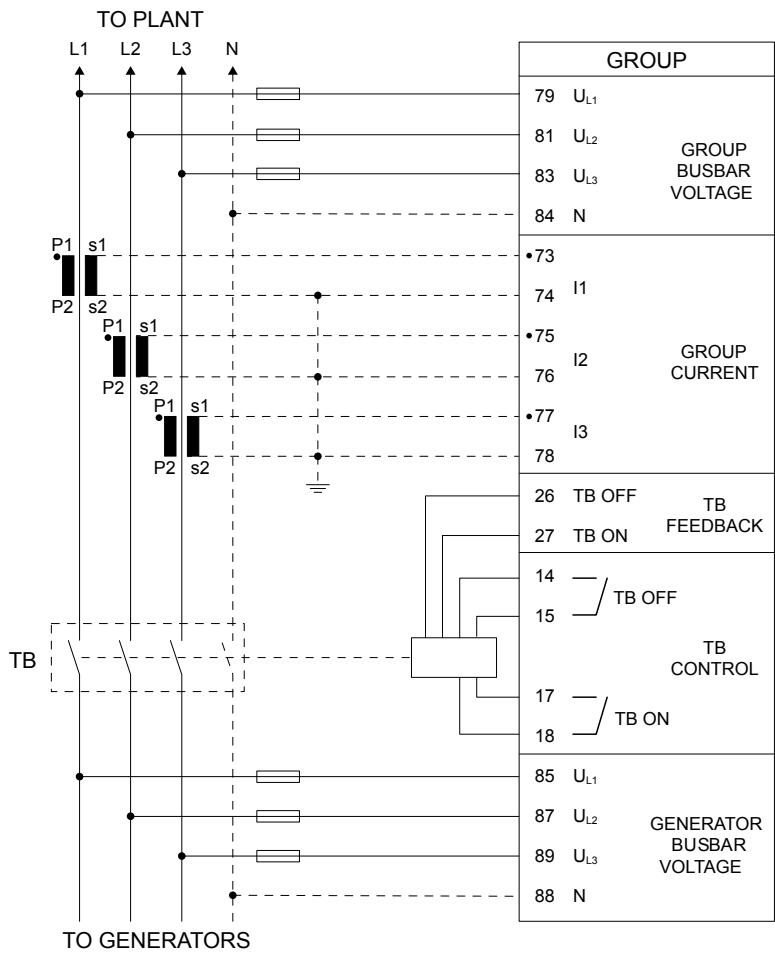
#### 4.1.3 Mains controller



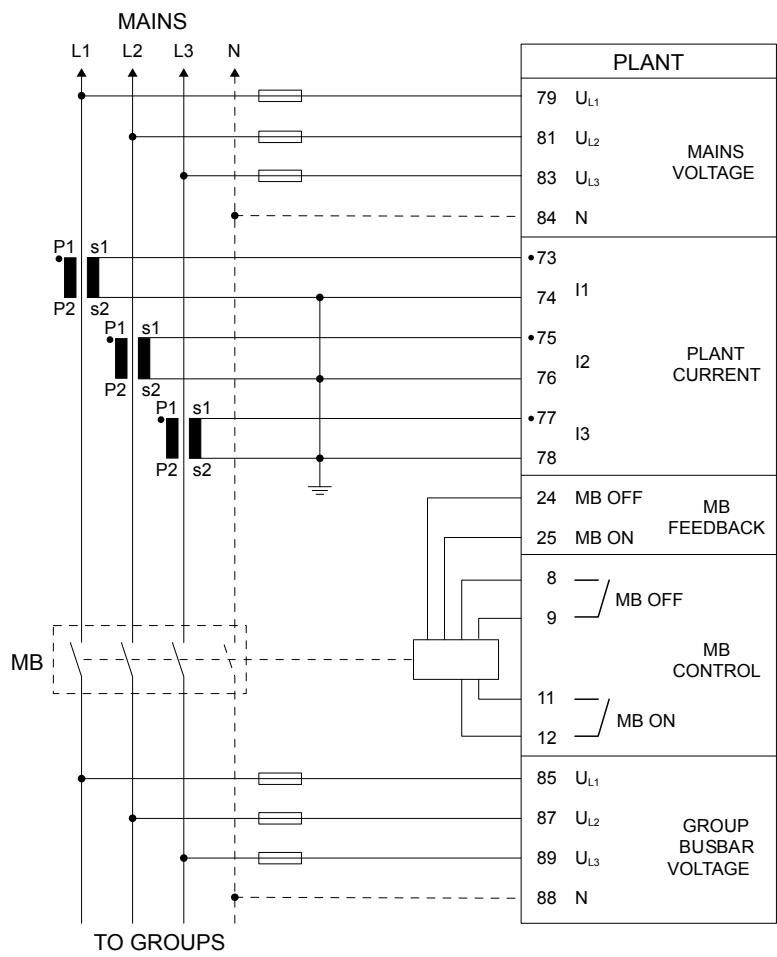
#### 4.1.4 BTB controller



#### 4.1.5 Group controller

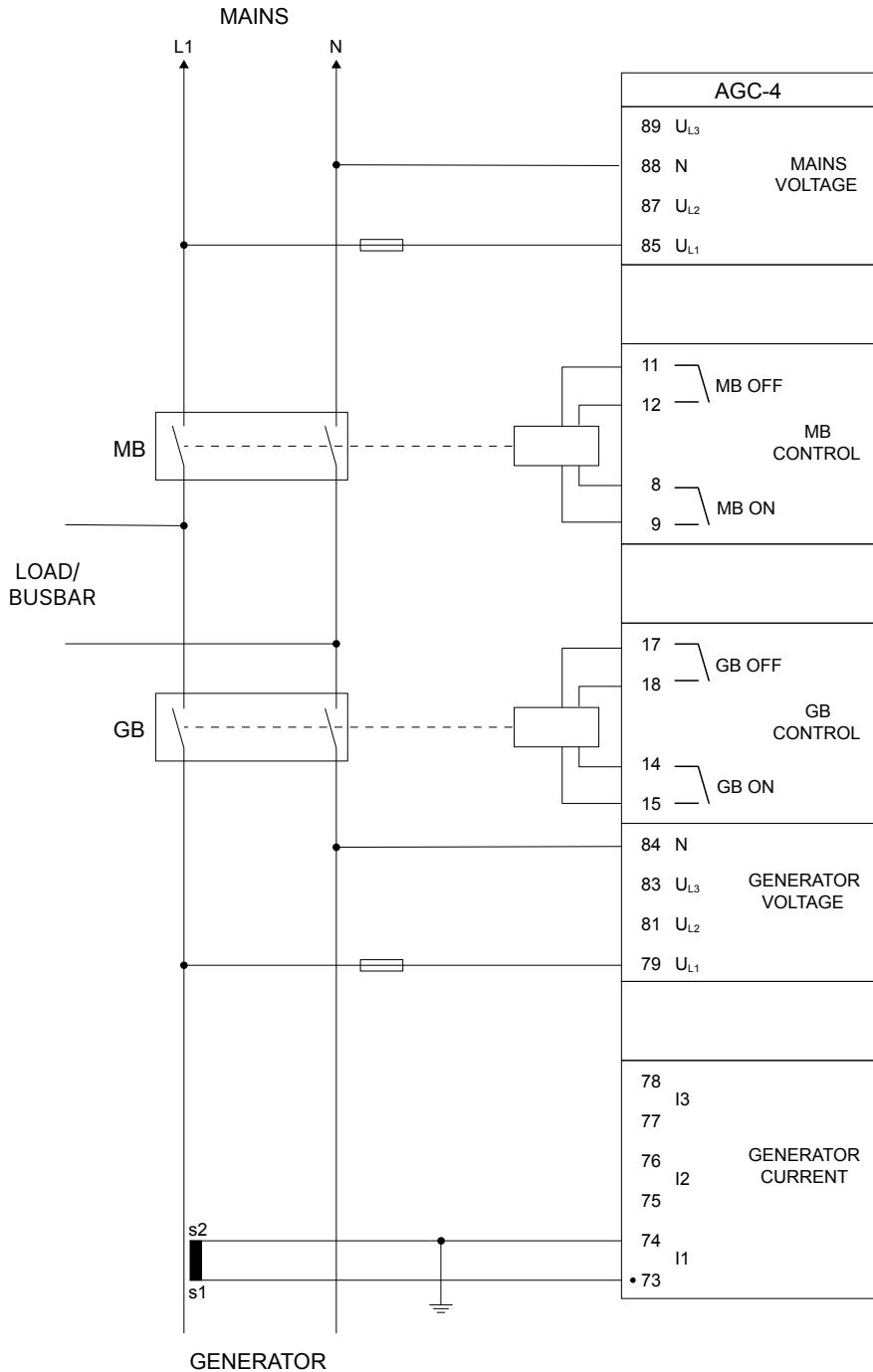


#### 4.1.6 Plant controller

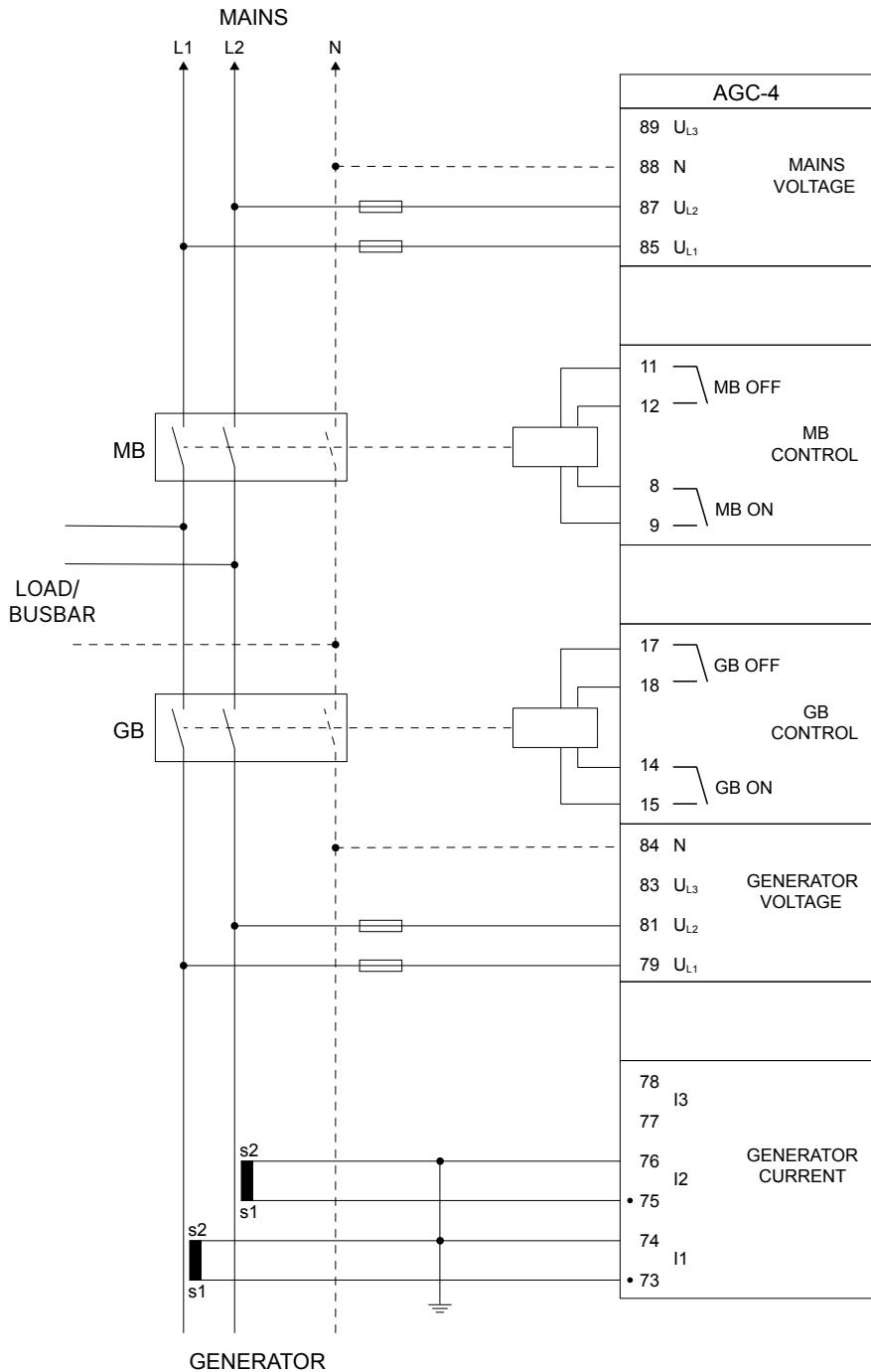


#### 4.1.7 Single-phase and 2-phase AC wiring

##### Single-phase (stand-alone genset controller)



## 2-phase L1L2 split-phase (stand-alone genset controller)



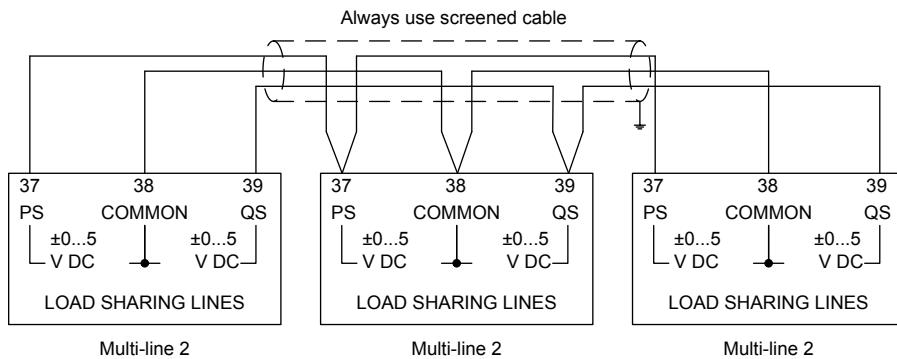
**NOTE** For split-phase, the waveforms are offset by a half-cycle ( $180^\circ$ ) from the neutral wire. Split-phase is also called L1-N-L2, or single phase in the USA.

## 4.2 DC connections

### 4.2.1 Fuse requirements (UL/cUL Listed)

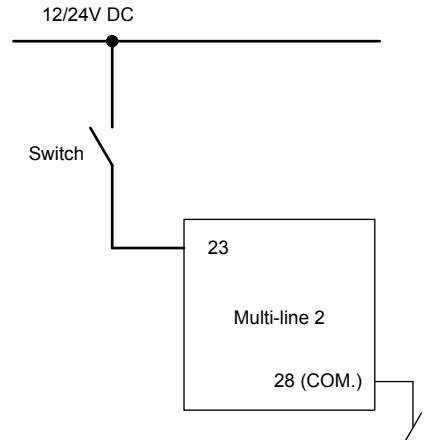
All inputs and outputs (except the AC voltage terminals): These must only be connected to limited voltage circuits from the engine starting battery protected by a 2 A DC max. time-delay fuse.

### 4.2.2 Load sharing lines (option G3)

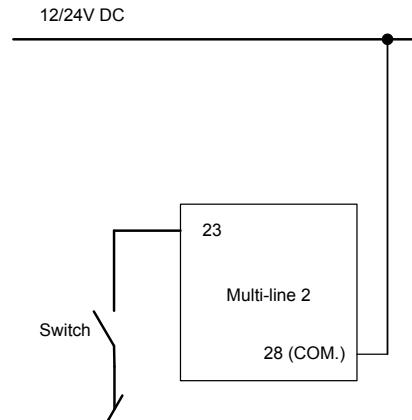


### 4.2.3 Digital inputs

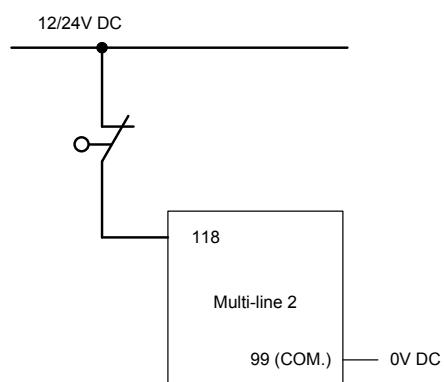
Battery positive to input:



Battery negative to input:



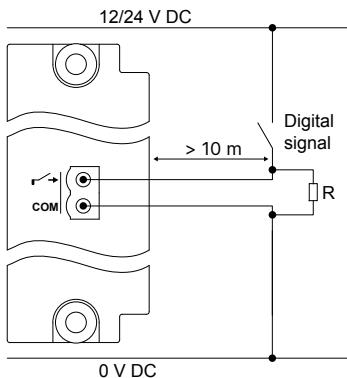
Emergency stop:



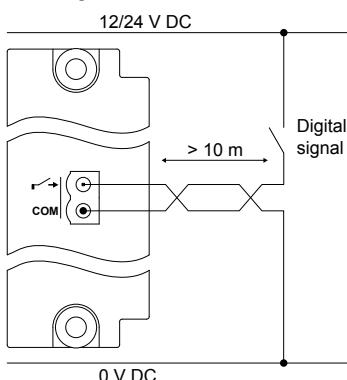
## Compliance with EN60255-26

If the wire to an open contact is over 10 m long, then additional measures are required for compliance with EN60255-26. You can use a  $1\text{ k}\Omega$  resistor to common, or you can use a twisted or shielded wire to the open contact.

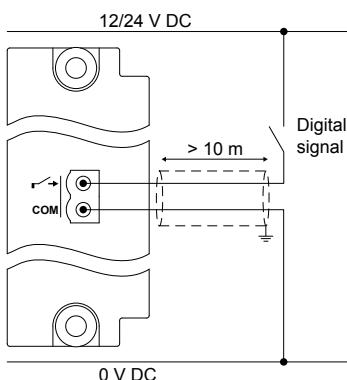
### Example: $1\text{ k}\Omega$ resistor to common for compliance with EN60255-26



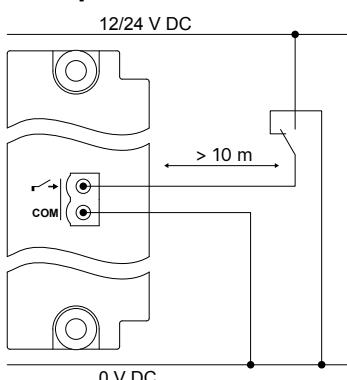
### Example: Twisted wire for compliance with EN60255-26



### Example: Shielded wire for compliance with EN60255-26

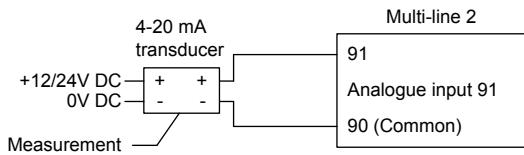


### Example: Closed contact for compliance with EN60255-26

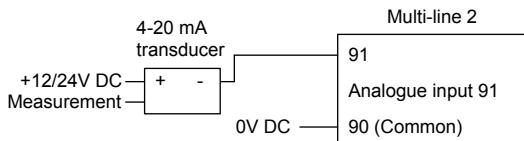


## 4.2.4 Analogue inputs (option M15.X)

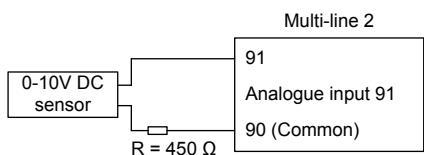
### 4 to 20 mA - Active transducer



### 4 to 20 mA - Passive transducer

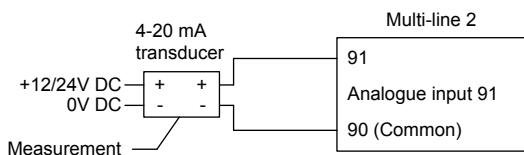


### V DC sensor

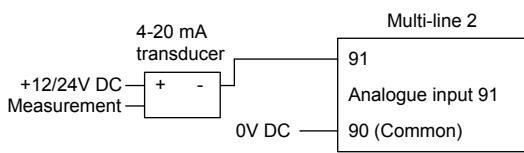


## 4.2.5 Multi-inputs (option M16.X)

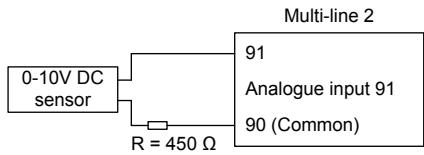
### 4 to 20 mA - Active transducer



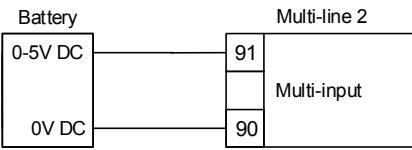
### 4 to 20 mA - Passive transducer



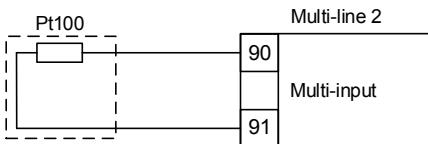
### V DC sensor



### 0 to 5 V DC



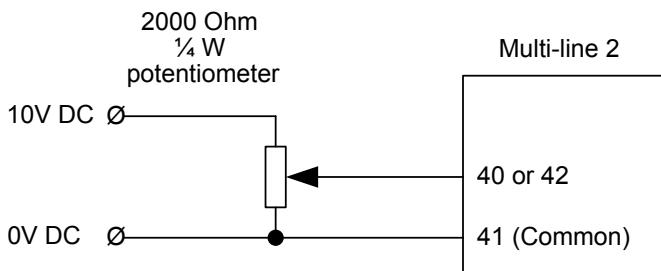
### Pt100



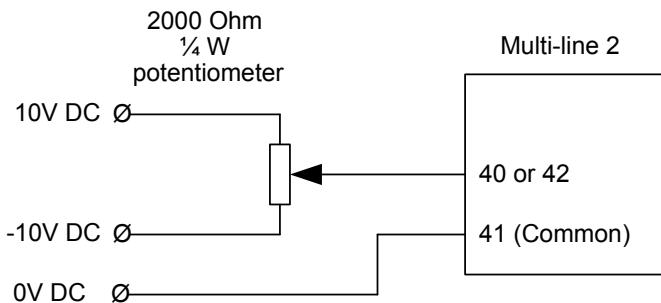
#### 4.2.6 External set points (option G3/M12)

The set point inputs are passive, that is, an external power source is needed. This can be an active output from, for example, a PLC, or a potentiometer can be used.

##### 0 to 10 V DC input using potentiometer



##### +/-10 V DC input using potentiometer

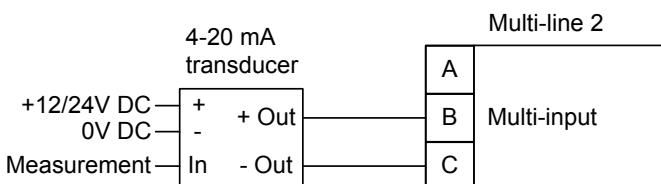


#### 4.2.7 Multi-inputs (102, 105, 108)

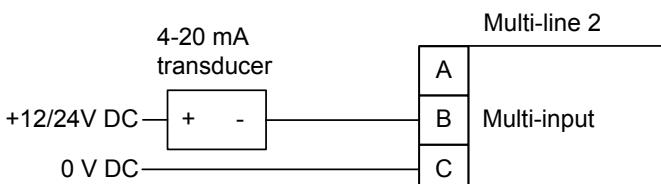
##### 0(4) to 20 mA

The multi-inputs are placed in slot #7. The terminal numbers for the individual multi-inputs can be seen under [Slot #7](#).

##### Active transducer

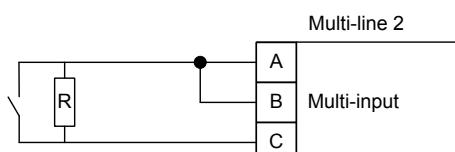


##### Passive transducer



**NOTE** If the passive sensor has its own battery supply, the voltage must not exceed 30 V DC.

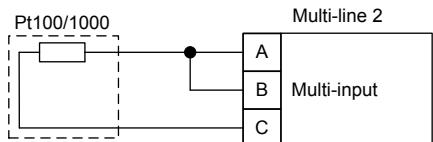
##### Digital inputs



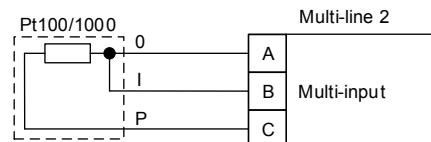
**NOTE** The resistor is only mounted if wire fail supervision is required. The value of the resistor should be 270 Ω +/-10 %.

## Pt100/Pt1000

2-wire

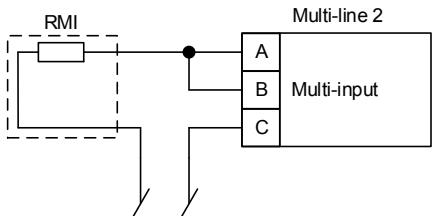


3-wire

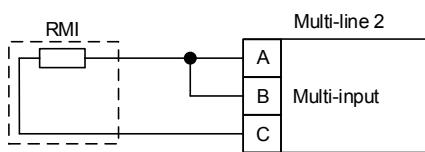


## RMI

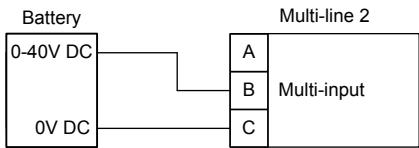
1-wire



2-wire

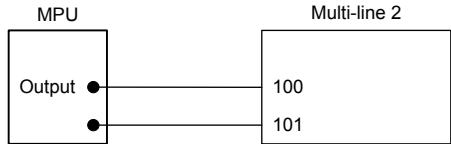


## 0 to 40 V DC

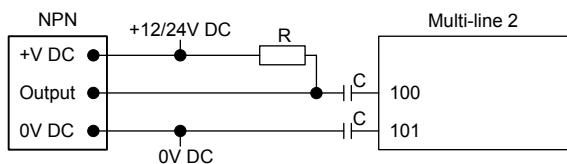


### 4.2.8 RPM input

#### Magnetic pickup (MPU)



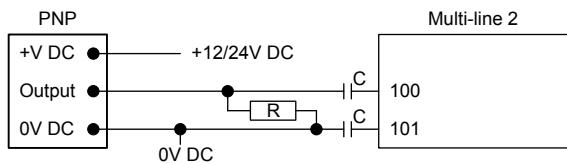
#### NPN sensor



$C = 22 \text{ nF}, 100 \text{ V foil type}$

$R = 1200 \Omega @ 24 \text{ V DC}, 600 \Omega @ 12 \text{ V DC}$

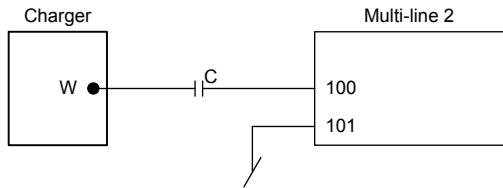
#### PNP sensor



$C = 22 \text{ nF}, 100 \text{ V foil type}$

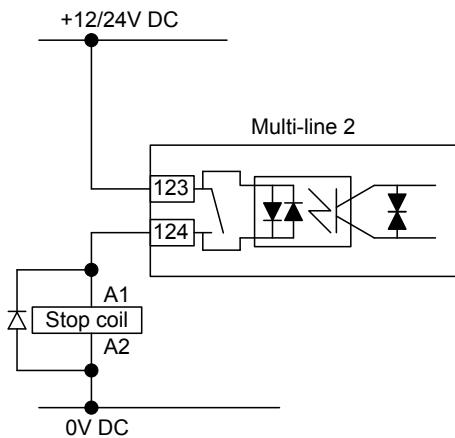
$R = 1200 \Omega @ 24 \text{ V DC}, 600 \Omega @ 12 \text{ V DC}$

## Charger, W output



C = 22 nF, 100 V foil type

## 4.2.9 Stop coil



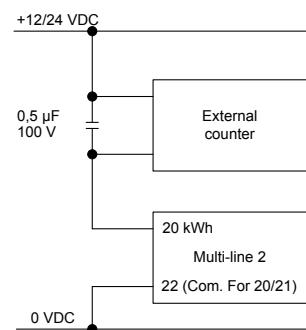
**NOTE** Remember to mount the freewheeling diode.

## 4.2.10 Transistor outputs (open collector outputs)

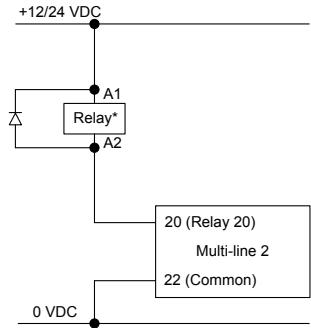
The open collector outputs can be used as kWh and kvarh counter outputs or as relay outputs. The outputs are low power outputs. For that reason, one of the following circuits must be applied.

Maximum load on the open collector outputs is 10 mA at 24 V DC.

### External counter

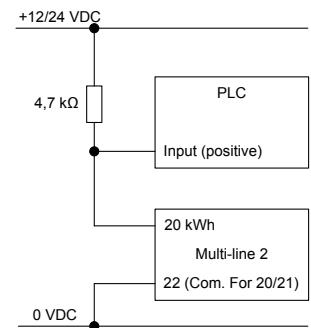


## Relay outputs



**NOTE** \* Remember to mount the freewheeling diode. If the external relay does not have a built-in diode, you can use a 1N4007 (1000 V/1 A) diode.

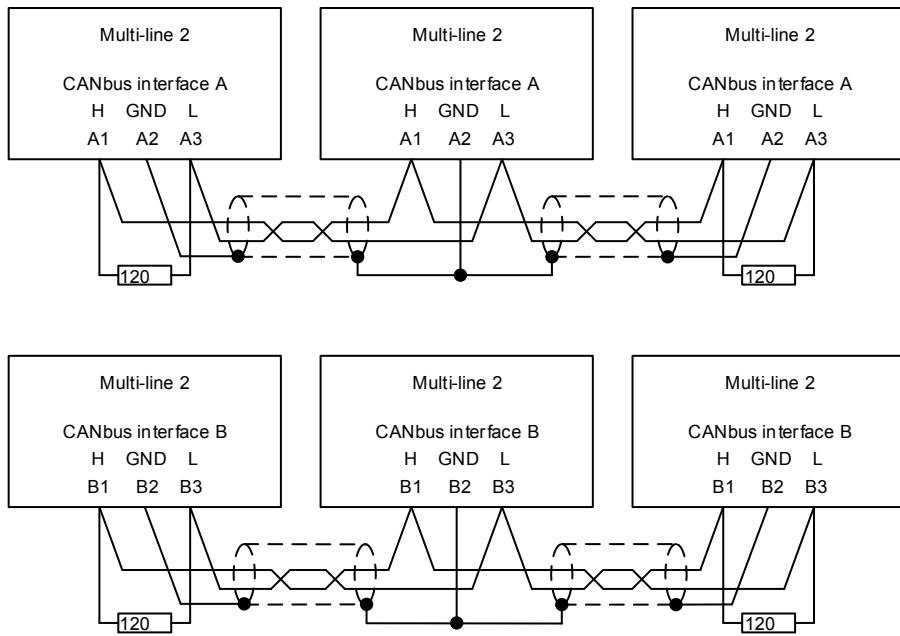
## Connection to PLC



## 4.3 Communication

### 4.3.1 CAN bus for power management (option G5)

Examples with three controllers connected (for example, one mains controller and two genset controllers).



**NOTE** Use shielded twisted cable.

**NOTE** End resistor R = 120 Ohm.

### 4.3.2 CAN bus for extended power management (option G7)

The CAN bus communication and the controllers must be wired as two separate systems.

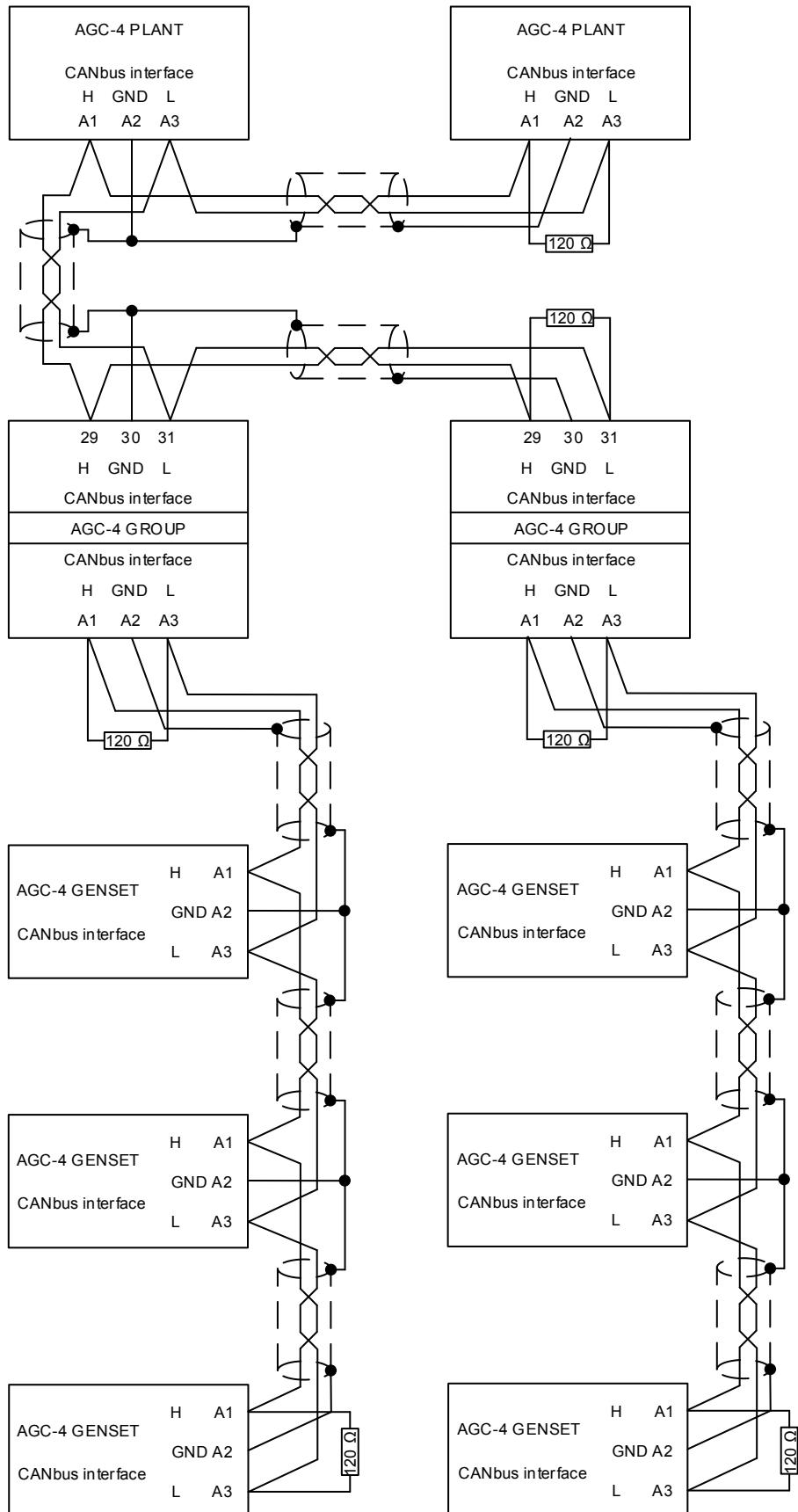
The first CAN bus is wired between the plant and group controller.

The other CAN bus line is wired from one group controller and down to the gensets in the specific genset group.

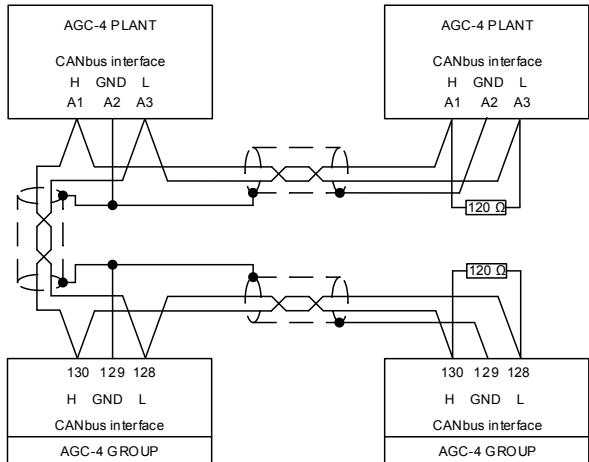
**NOTE** Use shielded twisted cable. Connect shield to earth at one end only. Shield ends must be insulated with tape or insulation tubing.

**NOTE** End resistor R = 120 ohm.

## Plant-Group-Genset CAN bus with option H12.2 in the group controller

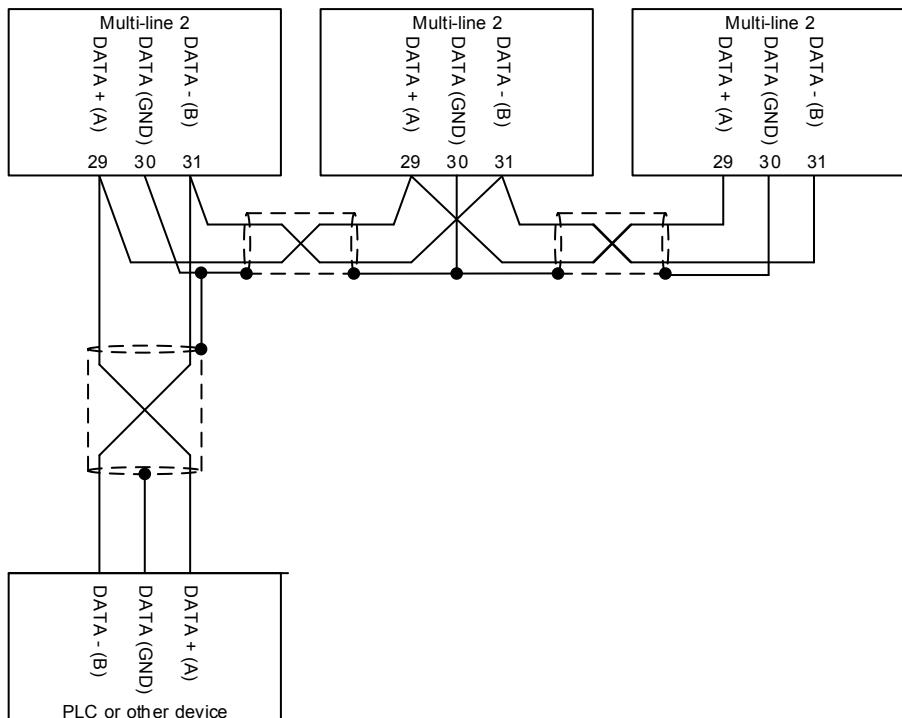


## Plant-Group CAN bus with option H12.8 in the group controller



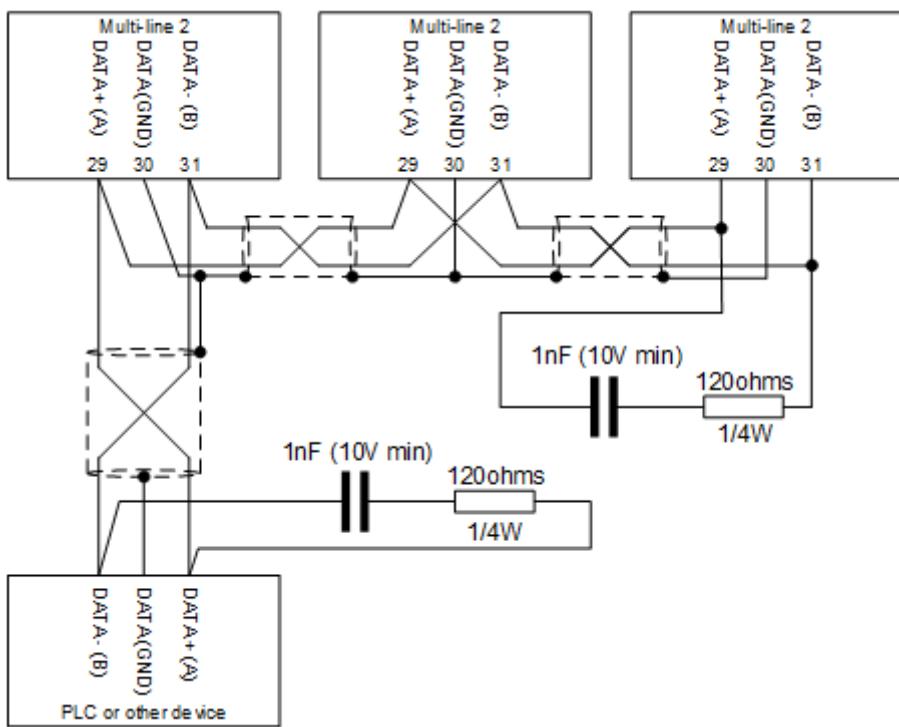
### 4.3.3 Modbus RS-485 (option H2)

#### Example with three controllers connected



**NOTE** Use shielded twisted cable.

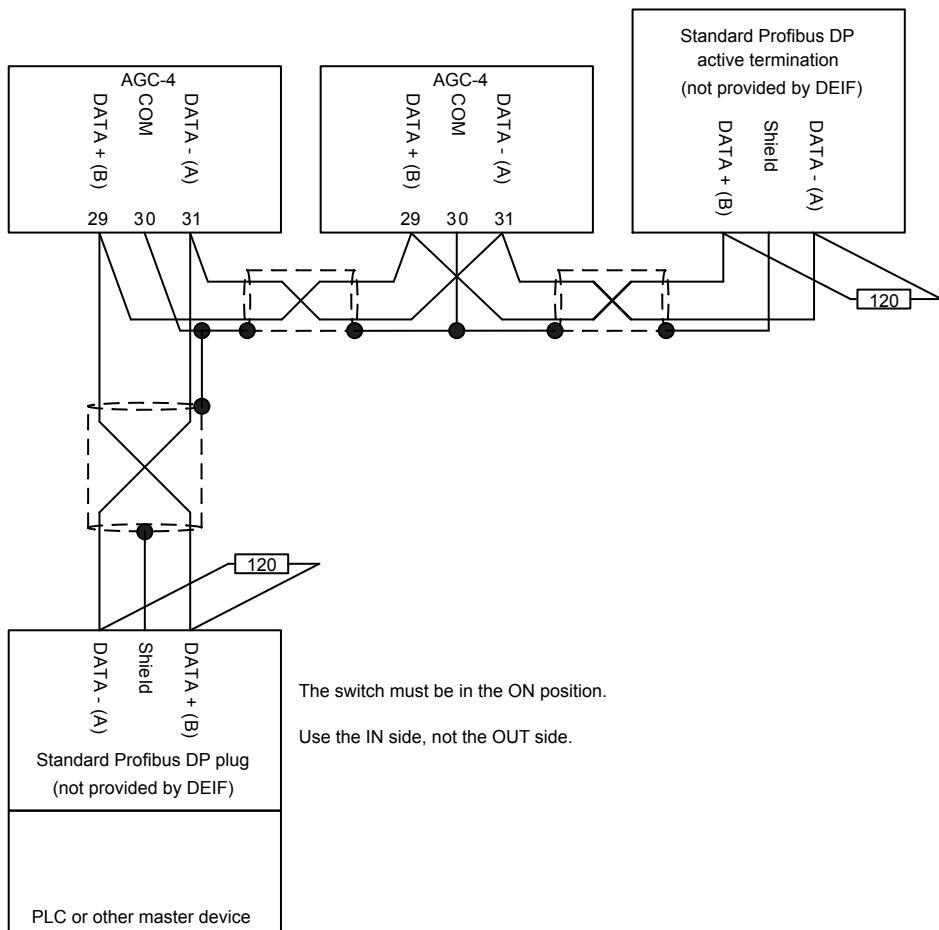
**RS-485 Modbus lines need end resistors (end terminators) when the bus length exceeds 30 m:**  
**Recommended installation**



**NOTE** Cable: Belden 3105A or equivalent. 22 AWG ( $0.6 \text{ mm}^2$ ) twisted pair, shielded,  $<40 \text{ m}\Omega/\text{m}$ , min. 95 % shield coverage.

#### 4.3.4 Profibus DP (option H3)

Example with two controllers connected.

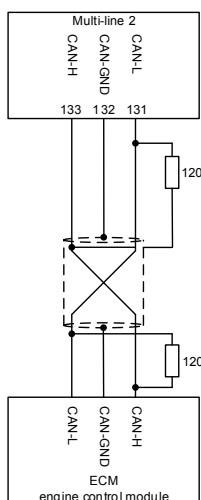


**NOTE** Use shielded twisted cable.

**NOTE** End resistor R = 120 Ohm.

#### 4.3.5 CAN bus engine communication (option H12.2/H12.8)

##### Wiring example for H12.8

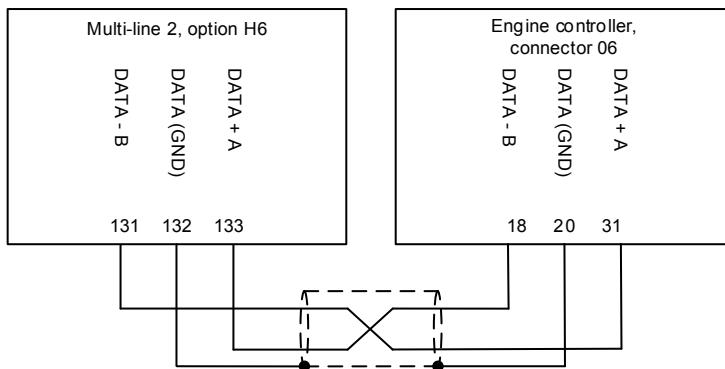


**NOTE** Use shielded twisted cable.

**NOTE** End resistor R = 120 Ohm.

**NOTE** The terminating resistor at the engine side might not be needed, see the engine manufacturer's literature.

#### 4.3.6 Cummins GCS (option H6)



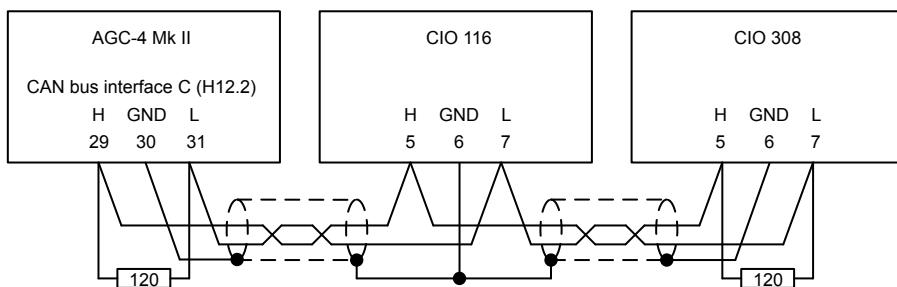
**NOTE** Use shielded twisted cable.

**NOTE** Cable: Belden 3105A or equivalent. 22 AWG ( $0.6 \text{ mm}^2$ ) twisted pair, shielded,  $<40 \text{ m}\Omega/\text{m}$ , min. 95 % shield coverage.

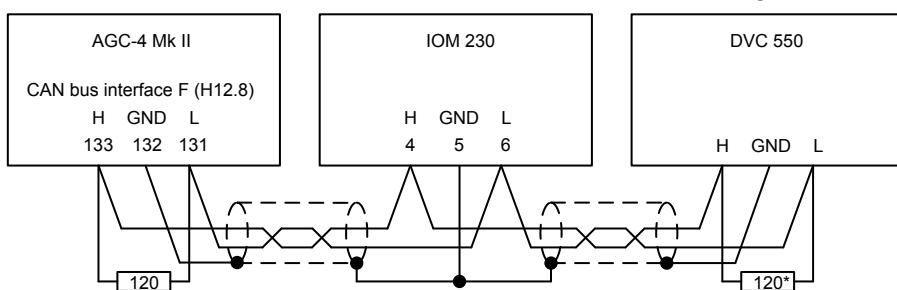
#### 4.3.7 External I/O module CIO/IOM (option H12.2/H12.8)

As long as the baud rate is the same, CAN bus communication to external CIOs or IOMs can be connected in series with CAN bus engine communication and DVC communication. That is, a number of CIO 116, 208, 308, and/or IOM 220, 230, can be connected in series on the CAN bus communication line.

##### CAN bus C communication to CIO 116 and CIO 308 example



##### CAN bus F communication to IOM 230 and DVC 550 example



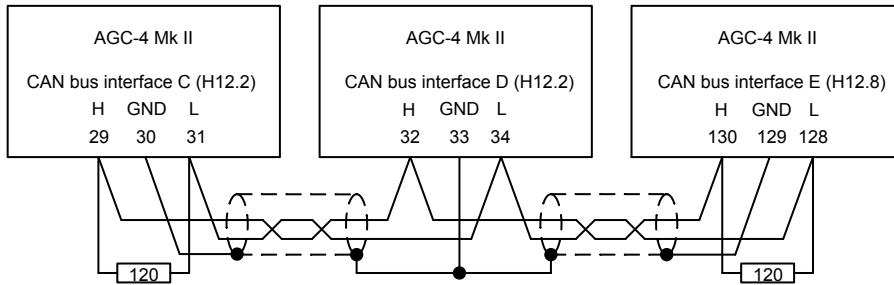
**NOTE** \* The connector supplied with the DVC 550 includes a 120 ohm end resistor.

#### 4.3.8 CANshare (option H12.2/H12.8)

Use the CAN bus C to F interfaces (on option H12.2 or H12.8) to connect the AGC-4 Mk II controllers in series for CANshare.

**NOTE** You do not have to use the same CAN bus interface in all of the controllers. However, using the same CAN bus interface is recommended.

## CANshare communication using CAN bus interfaces example

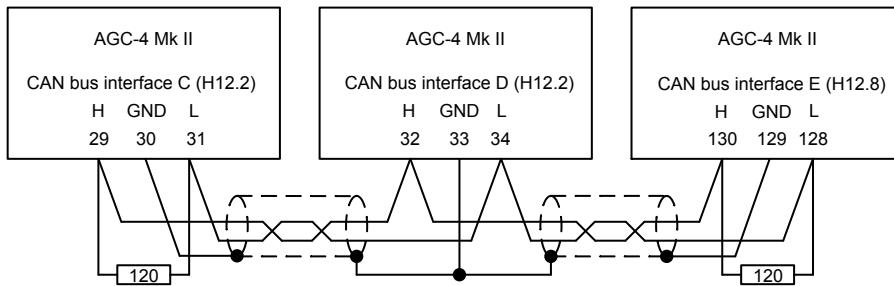


### 4.3.9 PMS lite (option H12.2/H12.8)

Use the CAN bus C to F interfaces (on option H12.2 or H12.8) to connect the AGC-4 Mk II PMS lite controllers in series.

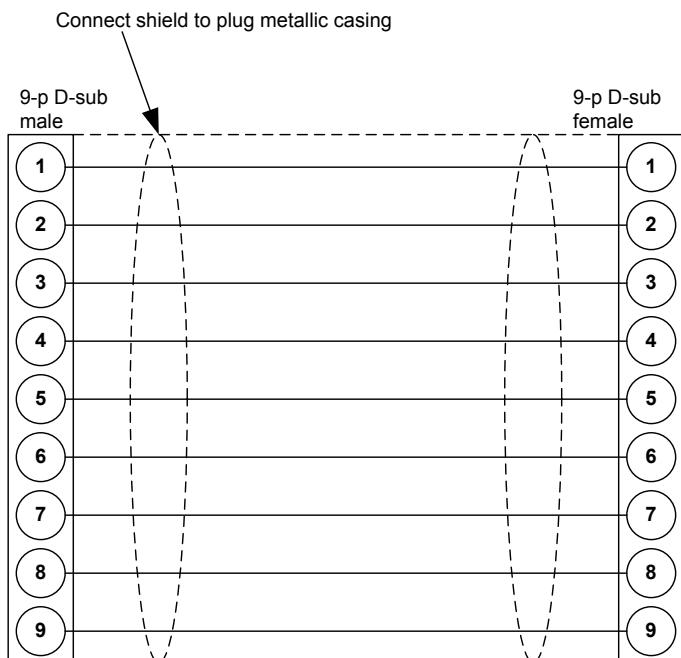
**NOTE** You do not have to use the same CAN bus interface in all of the controllers. However, using the same CAN bus interface is recommended.

## PMS lite communication using CAN bus interfaces example



### 4.3.10 Display cable (option J)

A standard computer extension cable can be used (9-pole D-sub male/female plugs) or a cable can be tailored.



Wires min. 0.22 mm<sup>2</sup>, max. cable length 6 m.

Cable types: Belden 9540, BICC H8146, Brand Rex BE57540 or equivalent.

**NOTE** Do not use tools or brute force when tightening the finger-screws on the display cable.

## 5. Technical specifications

### AC measurements and protections

The controller measures the voltage and current on one side of a breaker, and the voltage on the other side.

**Voltage measurements:** All voltages are phase-to-phase AC voltages. There are specifications for **Low** and **High** voltage ranges. The voltage range is determined by  $U_n$ . For terminals 79 to 84,  $U_n$  is the voltage transformer secondary in parameter 6042. For terminals 85 to 89,  $U_n$  is the voltage transformer secondary in parameters 6052/6062. For voltages below the truncation level, 0 V is shown.

**Current measurements:** All currents are AC currents. There are specifications for **Low** and **High** current ranges. The current range is determined by  $I_N$ , the current transformer secondary in parameter 6044. For currents below the truncation level, 0 A is shown.

The voltage range is independent of the current range, and vice versa.

All specifications are within the reference conditions, unless otherwise mentioned.

<b>Voltage measurements</b>	<p>Nominal value (<math>U_n</math>): 100 to 690 V. <b>Low:</b> <math>100 \leq U_n \leq 240</math> V <b>High:</b> <math>240 &lt; U_n \leq 690</math> V</p> <p>Reference range: <b>Low:</b> 65 to 324.0 V <b>High:</b> 156.7 to 931.5 V</p> <p>Measurement range: <b>Low:</b> 5.0 to 324.0 V, Truncation: 2 V <b>High:</b> 12.0 to 931.5 V, Truncation: 5 V</p> <p>Accuracy: <b>Low:</b> 5.0 to 324.0 V: <math>\pm 0.5\%</math> or <math>\pm 0.5</math> V (whichever is greater) <b>High:</b> 12.0 to 931.5 V: <math>\pm 0.5\%</math> or <math>\pm 1.2</math> V (whichever is greater)</p> <p>UL/cUL Listed: 600 V AC phase-phase Consumption: Maximum 0.25 VA/phase</p>
<b>Voltage and altitude</b>	<p>Operating altitude: 0 to 4000 m above sea level 2001 to 4000 m: Maximum 480 V AC phase-phase for measuring 3W4 voltage. No derating for 3W3.</p>
<b>Voltage withstand</b>	<p><math>U_n + 35\%</math> continuously <math>U_n + 45\%</math> for 10 seconds</p>
<b>Current measurements</b>	<p>Nominal value (<math>I_N</math>): <b>Low:</b> 1 A AC from current transformer <b>High:</b> 5 A AC from current transformer</p> <p>Measurement range: <b>Low:</b> 0.005 to 4.0 A, Truncation: 4 mA <b>High:</b> 0.025 to 20.0 A, Truncation: 20 mA</p> <p>Accuracy: <b>Low:</b> 0.005 to 4.0 A: <math>\pm 0.5\%</math> or <math>\pm 5</math> mA (whichever is greater) <b>High:</b> 0.025 to 20.0 A: <math>\pm 0.5\%</math> or <math>\pm 25</math> mA (whichever is greater)</p> <p>UL/cUL Listed: From listed or R/C (XODW2.8) current transformers 1 or 5 A Consumption: Maximum 0.3 VA/phase</p>

<b>Current withstand</b>	10 A continuous 20 A for 1 minute $20 \times I_N$ for 10 seconds (maximum 75 A) $80 \times I_N$ for 1 second (maximum 300 A)
<b>Frequency measurements</b>	Nominal value: 50 Hz or 60 Hz Reference range: 45 to 66 Hz Measurement range: 10 to 75 Hz
	<b>System frequencies</b> Accuracy: 45 to 66 Hz $\pm 10$ mHz, within the temperature operating range and the voltage range: <ul style="list-style-type: none"><li>• <b>Low:</b> 30 to 324.0 V</li><li>• <b>High:</b> 72 to 931.5 V</li></ul>
	<b>Phase frequencies</b> Accuracy: 45 to 66 Hz: $\pm 15$ mHz, within the temperature operating range 10 to 75 Hz: $\pm 50$ mHz, within the temperature operating range
<b>Phase angle (voltage) measurement</b>	Measurement range: -179.9 to 180°  Accuracy: -179.9 to 180°: 0.2°, within the temperature operating range
<b>Power measurement</b>	Accuracy: $\pm 0.5$ % of measured value or $\pm 0.5$ % of $U_n * I_N$ , whichever is greater, within the current measurement range
<b>Temperature and accuracy</b>	Reference range: 15 to 30 °C (59 to 86 °F) Reference range option Q2 (AC voltage only): -25 to 60 °C (-13 to 140 °F) Operating range: -25 to 70 °C (-13 to 158 °F)
	Temperature-dependent accuracy outside the reference range: Voltage: Additional: $\pm 0.2$ %, or $\pm 0.2$ V ( <b>Low</b> ) / $\pm 0.5$ V ( <b>High</b> ) per 10 °C (18 °F) (whichever is greater) Current: Additional: $\pm 0.2$ %, or $\pm 2$ mA ( <b>Low</b> ) / $\pm 10$ mA ( <b>High</b> ) per 10 °C (18 °F) (whichever is greater) Power: Additional: $\pm 0.2$ %, or $\pm 0.2$ % of $U_n * I_N$ per 10 °C (18 °F) (whichever is greater)

## General specifications

<b>Aux. supply</b>	Terminals 1 and 2: 12/24 V DC nominal (8 to 36 V DC operational). Maximum 11 W consumption Battery voltage measurement accuracy: $\pm 0.8$ V within 8 to 32 V DC, $\pm 0.5$ V within 8 to 32 V DC @ 20 °C Terminals 98 and 99: 12/24 V DC nominal (8 to 36 V DC operational). Maximum 5 W consumption 0 V DC for maximum 10 ms when coming from at least 24 V DC (cranking dropout) The aux. supply inputs are to be protected by a 2 A time-delay fuse. UL/cUL Listed: AWG 24
<b>Digital inputs</b>	Optocoupler, bi-directional ON: 8 to 36 V DC Impedance: 4.7 kΩ OFF: <2 V DC
<b>Analogue inputs</b>	-10 to +10 V DC: Not galvanically separated. Impedance: 100 kΩ (analogue load sharing lines) 0(4) to 20 mA: Impedance 50 Ω. Not galvanically separated (M15.X)
<b>RPM</b>	RPM (MPU): 2 to 70 V AC, 10 to 10000 Hz, maximum 50 kΩ
<b>Multi-inputs</b> Engine interface board slot #7	0(4) to 20 mA: 0 to 20 mA, $\pm 1$ %. Not galvanically separated Digital: Maximum resistance for ON detection: 100 Ω. Not galvanically separated Pt100/1000: -40 to 250 °C, $\pm 1$ %. Not galvanically separated. To EN/IEC60751 RMI: 0 to 1700 Ω, $\pm 2$ %. Not galvanically separated V DC: 0 to 40 V DC, $\pm 1$ %. Not galvanically separated
<b>Multi-inputs</b> (M16.X)	0(4) to 20 mA: 0 to 20 mA, $\pm 2$ %. Not galvanically separated Pt100: -40 to 250 °C, $\pm 2$ %. Not galvanically separated. To EN/IEC60751

	V DC: 0 to 5 V DC, $\pm 2\%$ . Not galvanically separated
<b>Relay outputs</b>	<p>Electrical rating: 250 V AC/30 V DC, 5 A.            UL/cUL Listed: 250 V AC/24 V DC, 2 A resistive load            Thermal rating @ 50 °C: 2 A: Continuously. 4 A: <math>t_{on} = 5</math> seconds, <math>t_{off} = 15</math> seconds.            (Controller status output: 1 A)</p>
<b>Open collector outputs</b>	Supply: 8 to 36 V DC, maximum 10 mA (terminal 20, 21, 22 (com))
<b>Analogue outputs</b>	<p>0(4) to 20 mA and <math>\pm 25</math> mA. Galvanically separated. Active output (internal supply). Load maximum 500 <math>\Omega</math>.            UL/cUL Listed: Max. 20 mA output            Update rate: Transducer output: 250 ms. Regulator output: 100 ms</p> <p>Accuracy:            Analogue outputs: Class 1.0 according to total range            Option EF5: Class 4.0 according to total range            To EN/IEC60688</p>
<b>Load sharing lines</b>	-5 to 0 to +5 V DC. Impedance: 23.5 k $\Omega$
<b>Material</b>	All plastic materials are self-extinguishing according to UL94 V1
<b>Plug connections</b>	<p><b>Controller</b>            AC current: 0.75 to 4.0 mm<sup>2</sup> stranded wire. UL/cUL Listed: AWG 18            AC voltage: 0.5 to 2.5 mm<sup>2</sup> stranded wire. UL/cUL Listed: AWG 20            Relays: UL/cUL Listed: AWG 22            Terminals 98-116: 0.2 to 1.5 mm<sup>2</sup> stranded wire. UL/cUL Listed: AWG 24            Other: 0.2 to 2.5 mm<sup>2</sup> stranded wire. UL/cUL Listed: AWG 24</p> <p>Tightening torque: 0.5 N·m (5-7 lb-in)            Service port: USB B            Ethernet/Modbus TCP/IP connector: RJ-45</p> <p><b>DU-2 display</b>            9-pole D-sub female            Tightening torque: 0.2 N·m</p>
<b>Governors and AVRs</b>	<p>Interfaces to all governors and AVRs using analogue, relay control or CAN-based J1939 communication            See interfacing guide at <a href="http://www.deif.com">www.deif.com</a></p>
<b>Approvals</b>	<p>UL/cUL Listed to UL/ULC6200:2019 1.ed            See <a href="http://www.deif.com">www.deif.com</a> for the most recent approvals.</p>
<b>UL/cUL Listed</b>	<p><b>Controller</b>            A suitable type 1 (flat surface) enclosure is required:            Unventilated/ventilated with filters for controlled/pollution degree 2 environment            Flat surface mounting - Type 1 enclosure            Installation: To be installed in accordance with the NEC (US) or the CEC (Canada)            Use 90 °C copper conductors only            Wire Size: AWG 30-12            Tightening torque: 5-7 lb-in.            All inputs and outputs (except the AC voltage terminals): These must only be connected to limited voltage circuits from the engine starting battery protected by a 2 A DC max. time-delay fuse.            Communication circuits: Only connect to communication circuits of a listed system/equipment</p> <p><b>DU-2 Display</b>            Flat surface mounting - Type 1 enclosure            Power supply: The controller, or a separate Class 2 source</p> <p><b>AOP-2</b>            Wiring: Use 90 °C copper conductors only</p>

	<p>Mounting: For use on a flat surface of type 1 enclosure. Main disconnect must be provided by installer.</p> <p>Installation: To be installed in accordance with the NEC (US) or the CEC (Canada)</p> <p><b>DC/DC converter for AOP-2</b></p> <p>Tightening torque: 0.5 Nm (4.4 lb-in)</p> <p>Wire size: AWG 22-14</p> <p>Tightening torque: Panel door mounting 0.7 N·m, D-sub screw 0.2 N·m</p>
<b>Weight</b>	<p>Controller: 1.6 kg (3.5 lbs.)</p> <p>Option J1/J4/J6/J7: 0.2 kg (0.4 lbs.)</p> <p>Option J2: 0.4 kg (0.9 lbs.)</p> <p>Option J8: 0.3 kg (0.58 lbs.)</p> <p>DU-2 display or AOP: 0.4 kg (0.9 lbs.)</p>

For the TDU technical specifications, see the **TDU Data sheet**. For more information, see [www.deif.com/products/tdu-series](http://www.deif.com/products/tdu-series)

## 5.1 Environmental specifications

<b>Operating temperature</b> (including DU-2 display and AOP)	-25 to 70 °C (-13 to 158 °F) UL/cUL Listed: Max. surrounding air temperature: 55 °C (131 °F)
<b>Storage temperature</b> (including DU-2 display and AOP)	-40 to 70 °C (-40 to 158 °F)
<b>Climate</b>	97 % RH to IEC 60068-2-30
<b>Galvanic separation</b>	Between AC voltage and other I/Os: 3250 V, 50 Hz, 1 min. Between AC current and other I/Os: 2200 V, 50 Hz, 1 min. Between analogue outputs and other I/Os: 550 V, 50 Hz, 1 min. Between digital input groups and other I/Os: 550 V, 50 Hz, 1 min.
<b>Mounting</b>	DIN-rail mount or base mount with six screws Tightening torque: 1.5 N·m
<b>Safety</b>	To EN/IEC 61010-1, installation category (over-voltage category) III, 600 V, pollution degree 2 To EN/IEC 60255-27 over-voltage category III, 600 V, pollution degree 2 To UL/ULC 6200:2019 1.ed, over-voltage category III, 600 V, pollution degree 2
<b>EMC</b>	To EN/IEC 61000-6-2, EN/IEC 61000-6-4, EN/IEC 60255-26
<b>Vibration</b>	3 to 13.2 Hz: 2 mm <sub>pp</sub> . 13.2 to 100 Hz: 0.7 g. To IEC 60068-2-6 & IACS UR E10 10 to 58.1 Hz: 0.15 mm <sub>pp</sub> . 58.1 to 150 Hz: 1 g. To IEC 60255-21-1 Response (class 2) 10 to 150 Hz: 2 g. To IEC 60255-21-1 Endurance (class 2) 3 to 8.15 Hz: 15 mm <sub>pp</sub> . 8.15 - 35 Hz 2g. To IEC 60255-21-3 Seismic (class 2)
<b>Shock (base mount)</b>	10 g, 11 ms, half sine. To IEC 60255-21-2 Response (class 2) 30 g, 11 ms, half sine. To IEC 60255-21-2 Endurance (class 2) 50 g, 11 ms, half sine. To IEC 60068-2-27
<b>Bump</b>	20 g, 16 ms, half sine. To IEC 60255-21-2 (class 2)
<b>Protection</b>	Controller: IP20. DU-2 display and AOP: IP40 (IP54 with gasket: Option L). UL/cUL Listed: Type Complete Device, Open Type. To EN/IEC 60529